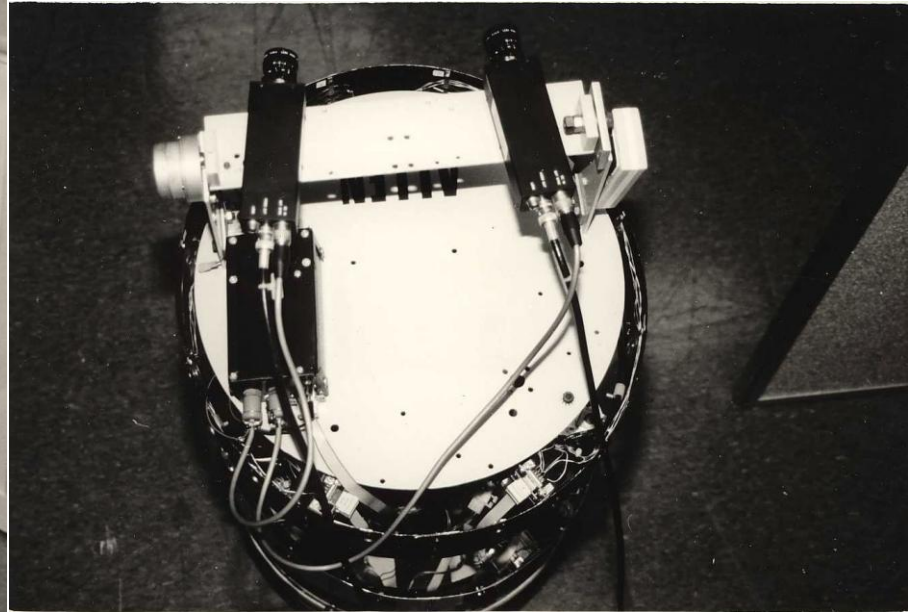
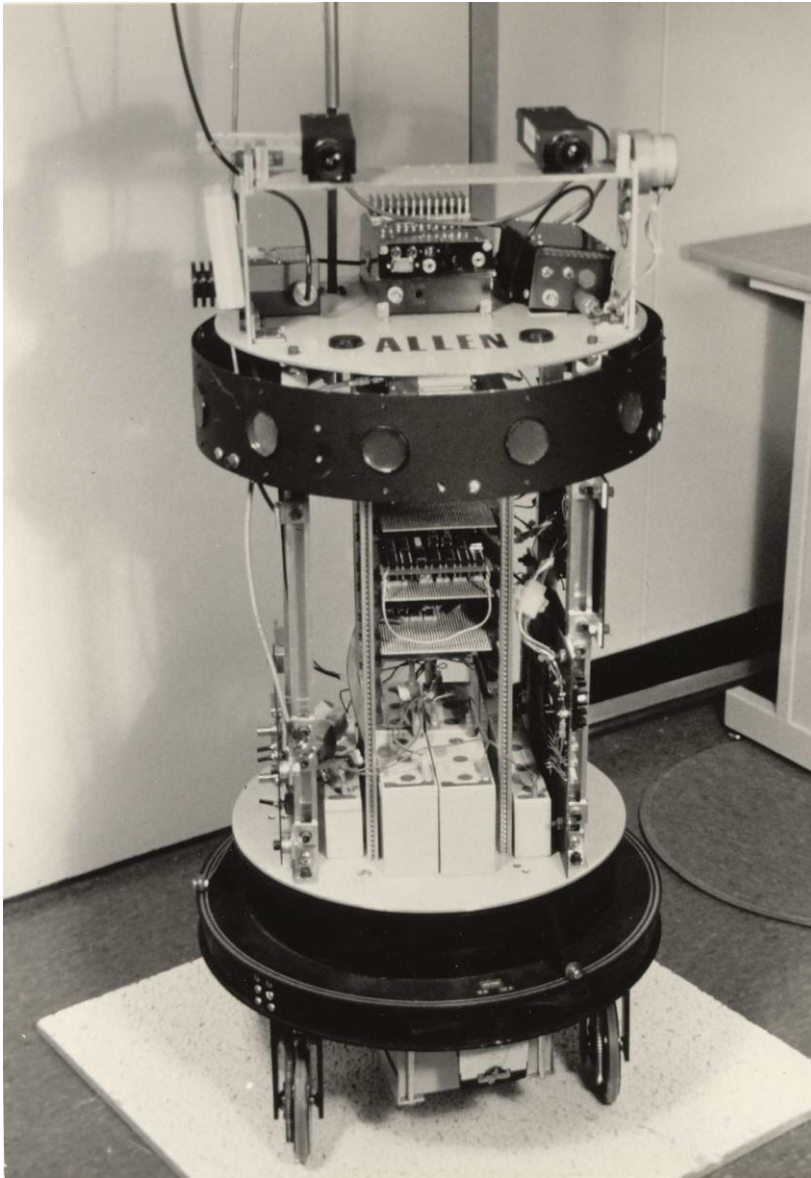


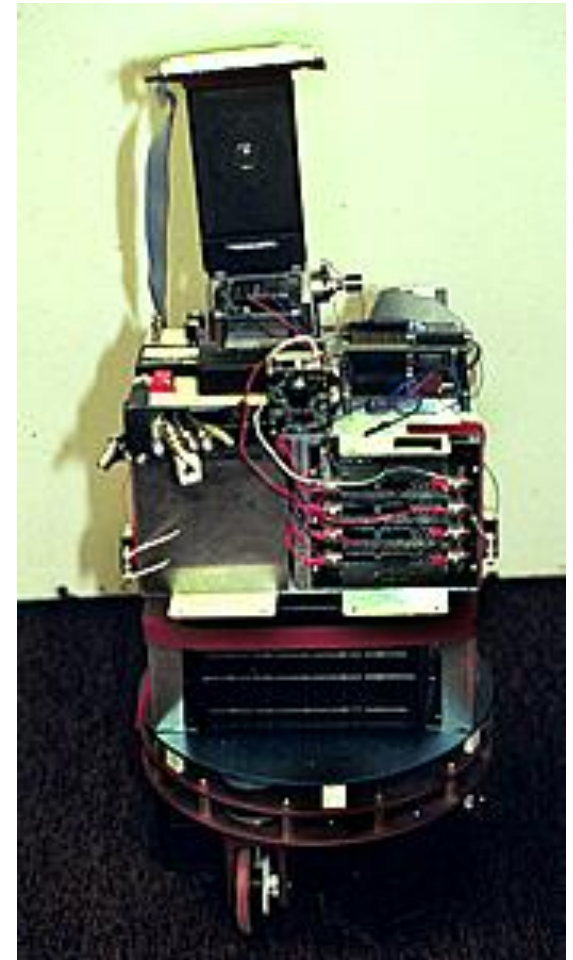
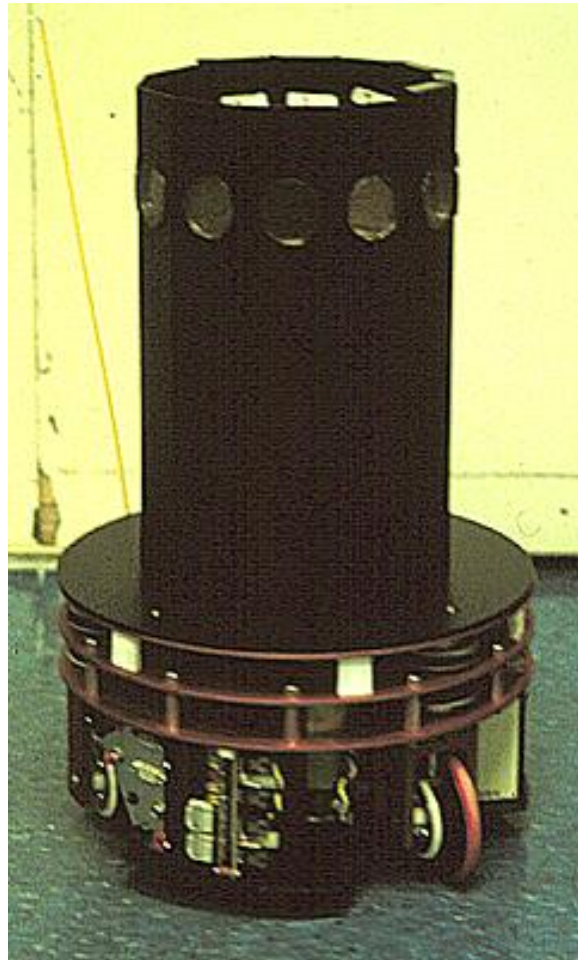
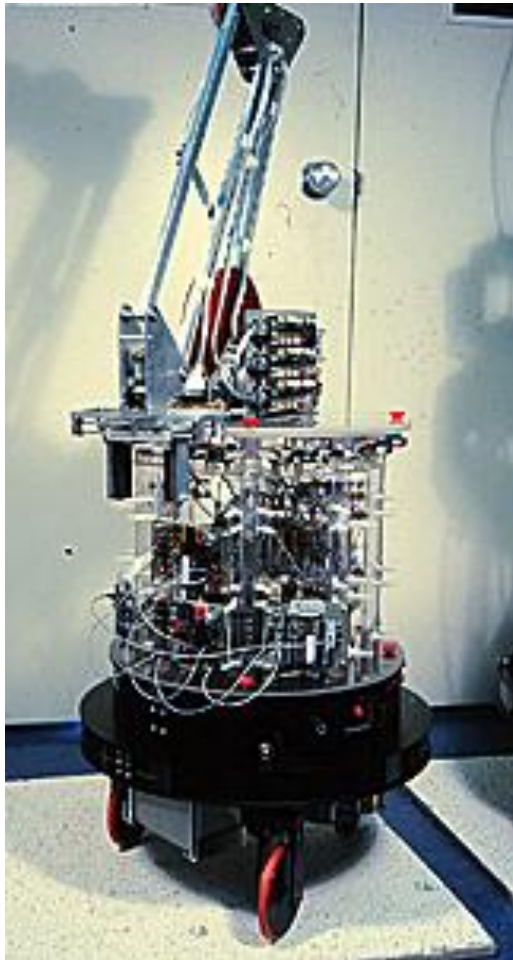


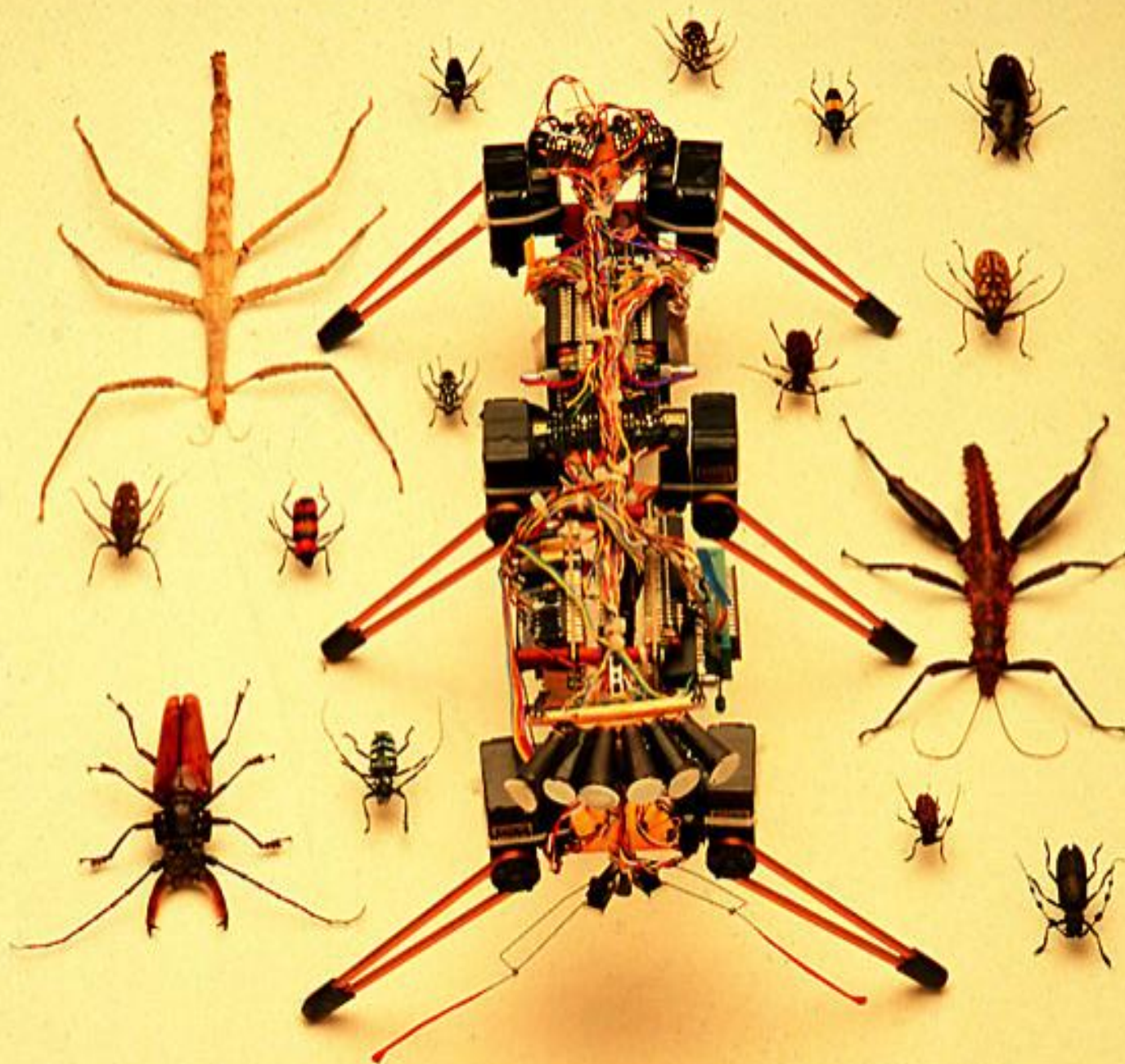
July 3, 2015

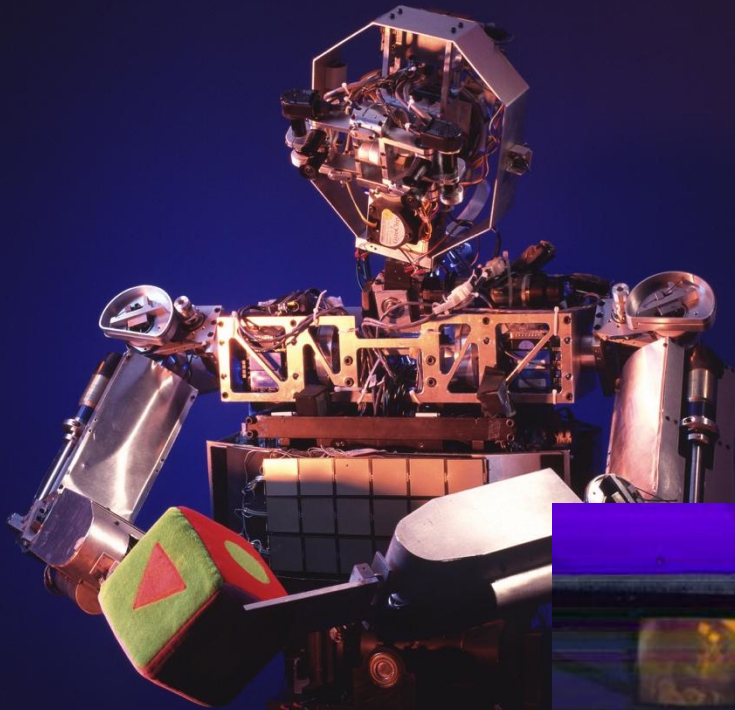
# ADDING A LITTLE INTELLIGENCE TO FACTORY ROBOTS

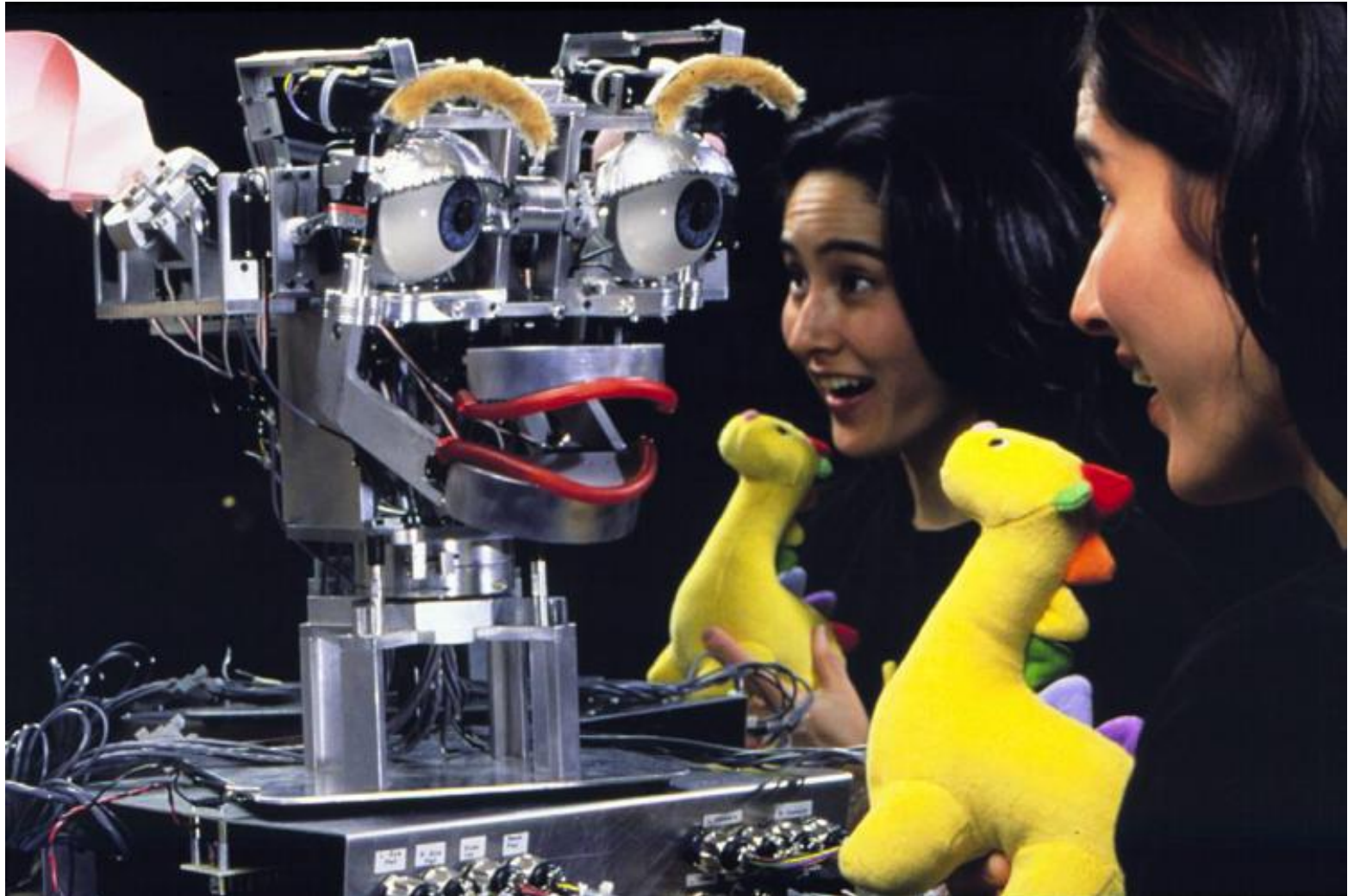
RODNEY BROOKS

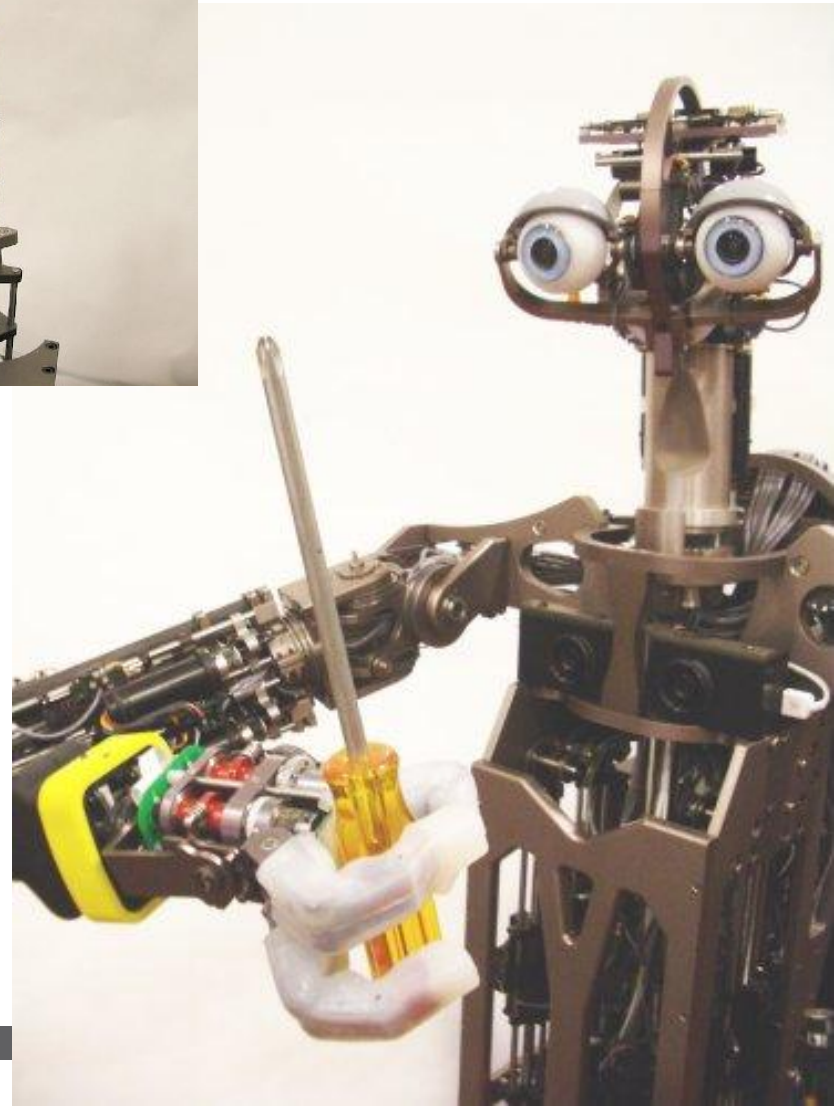
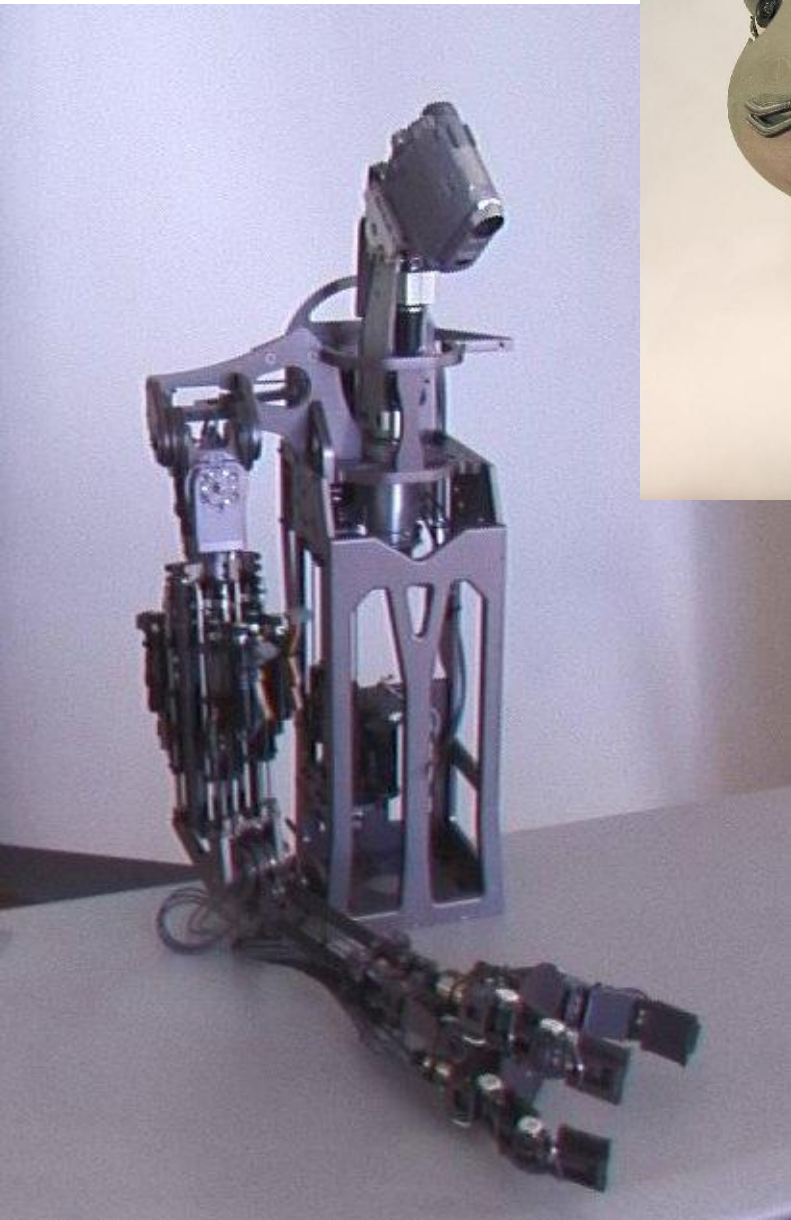
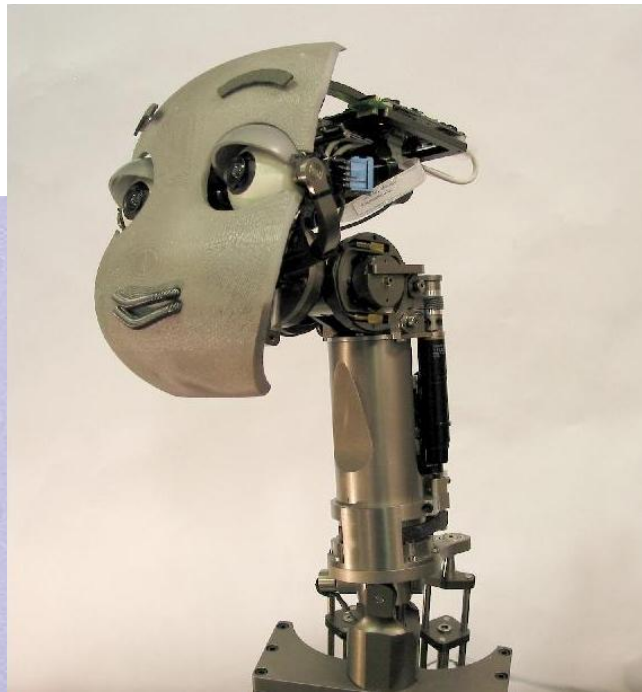


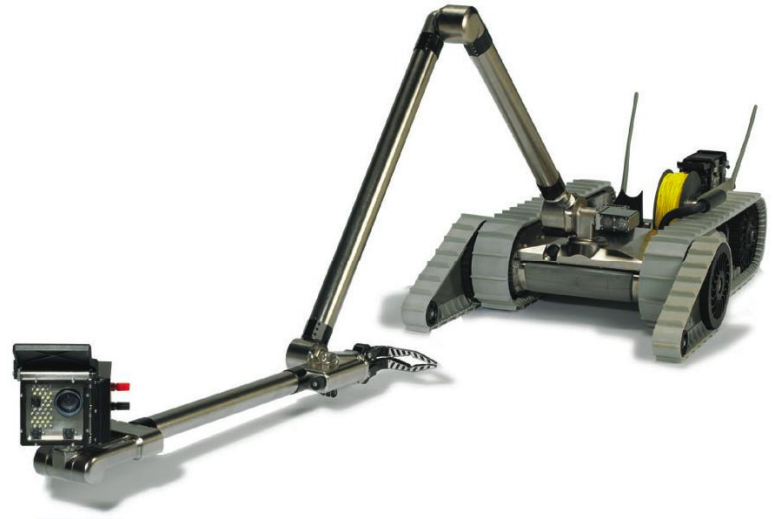
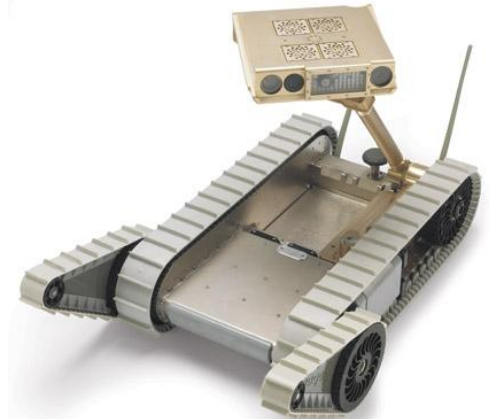






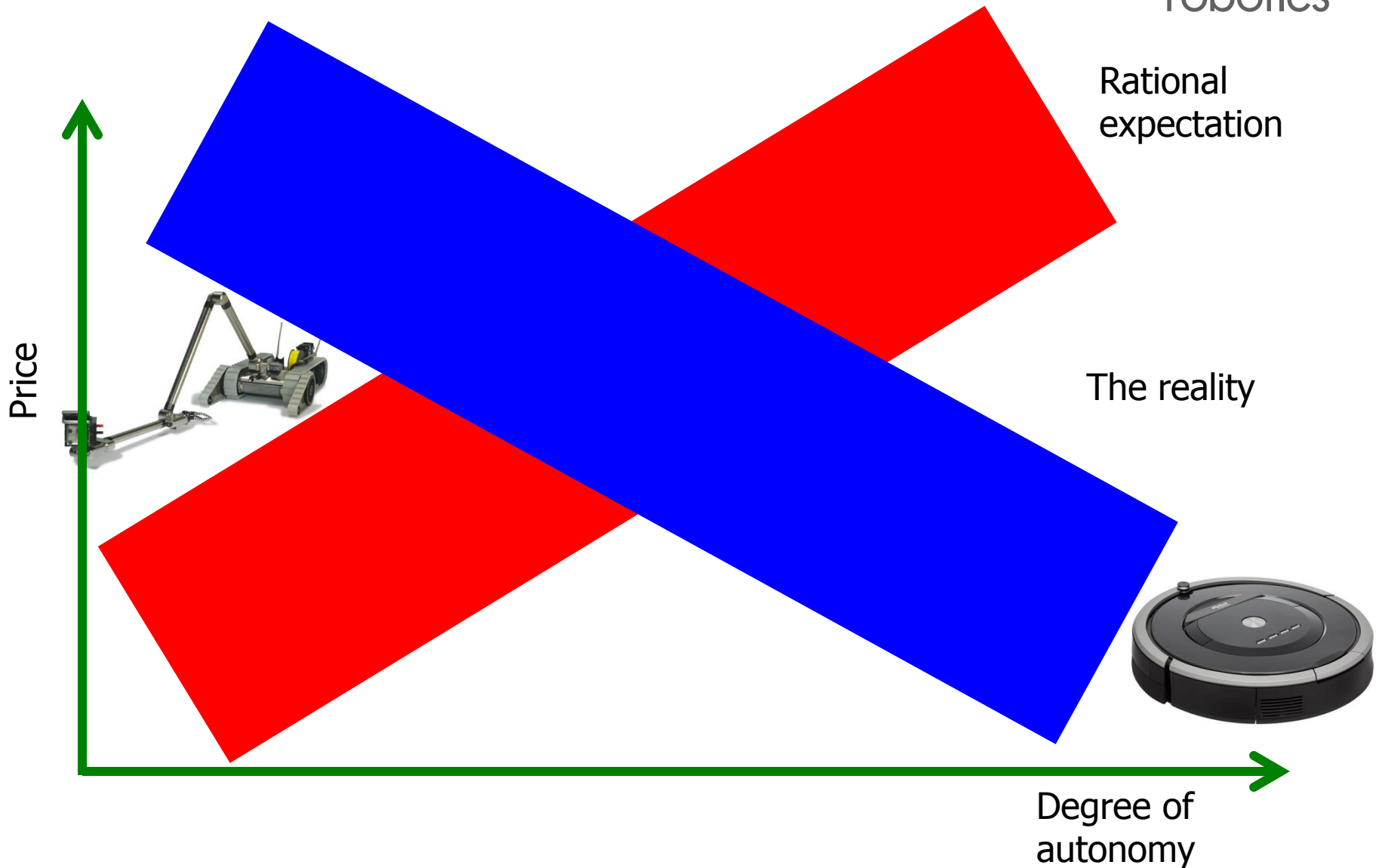








# AUTONOMY VS. PRICE OF ROBOT



# IROBOT ROOMBA



# THE ROOMBA WAS NOT THE FIRST HOME CLEANING ROBOT



Electrolux Trilobite: 2,000 Euros



iRobot Roomba: \$200

# EVOLUTION OF THE ROOMBA INTERFACE





Quality corner 質量角 Quality corner

Quality corner 質量角 Quality corner

 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>
 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>
 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>

 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>
 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>
 <p>Text</p>	 <p>Text</p>	 <p>Text</p>	 <p>Text</p>

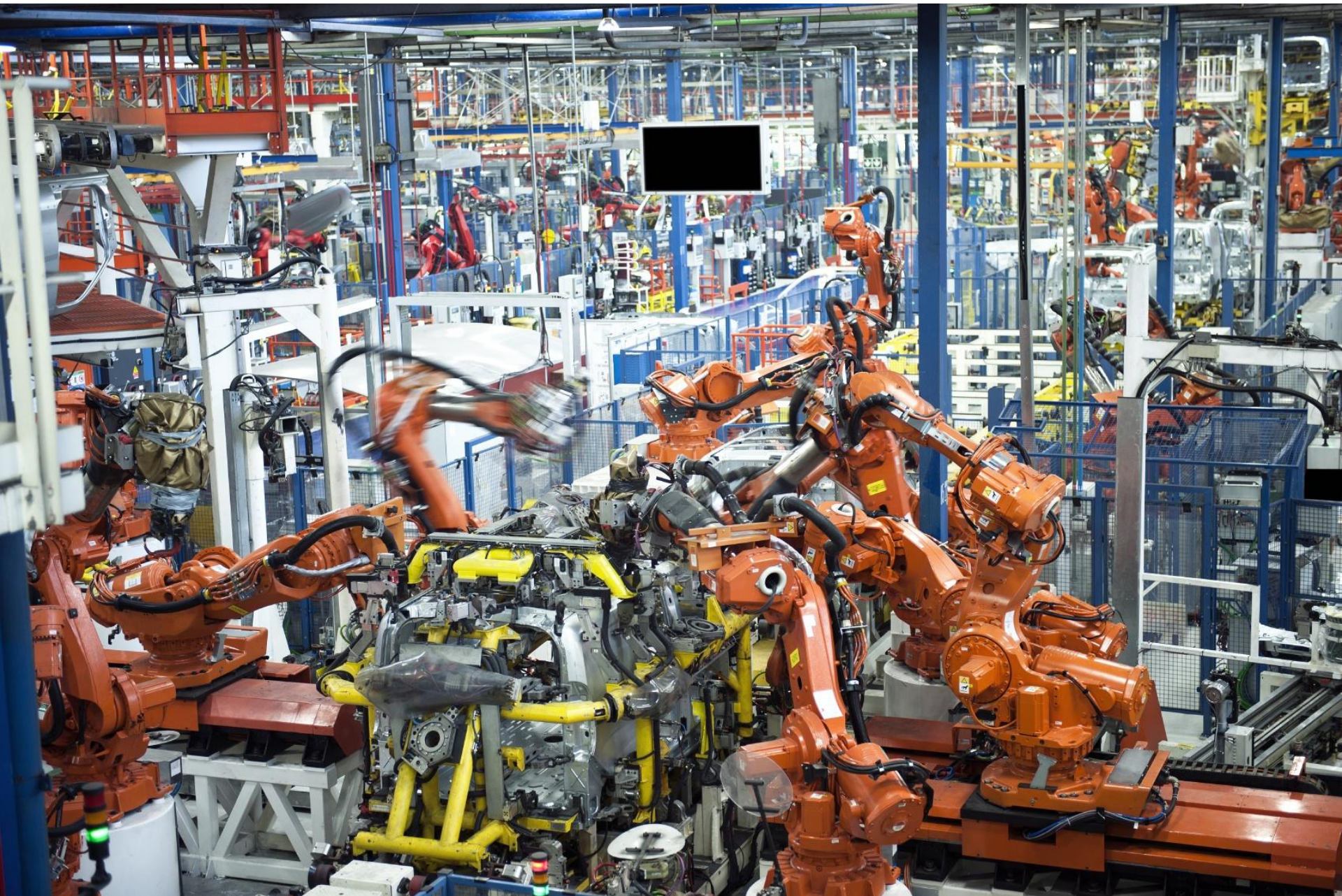


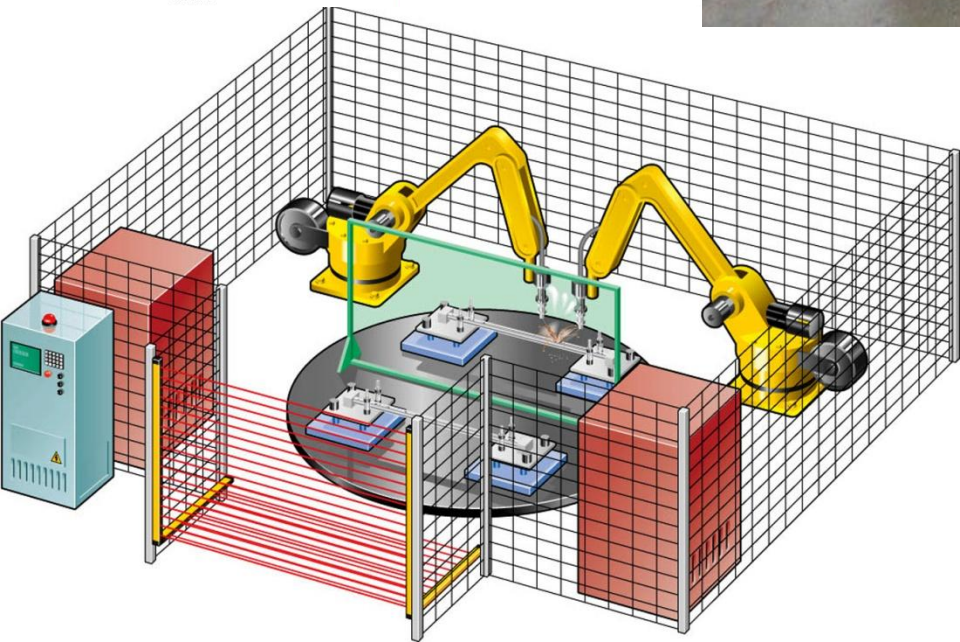


# US Manufacturing Since WW2

















# A NEW CATEGORY OF ROBOT

Smart . Simple . Fast . Cheap

Software + Sensing = Intelligence

Simple, ubiquitous, manual tasks

Fast deployment and change-over

Payback in a year

Safe around people

Robots in the field

## Large Manufacturers



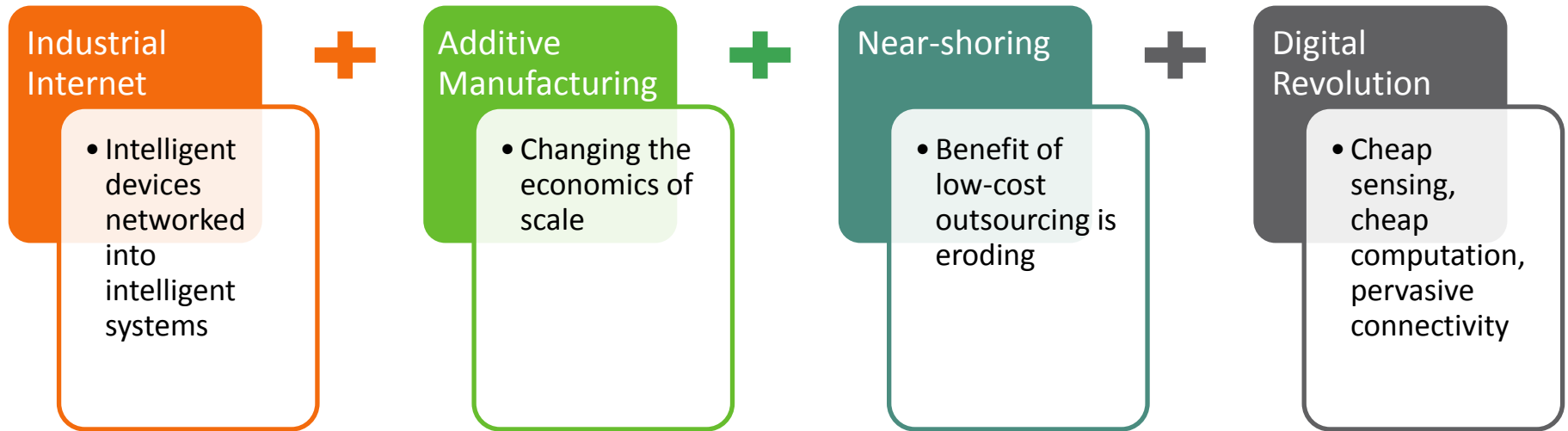
## Small & Medium Enterprise



## Research & Education



# CONVERGENCE: THE TIME IS NOW



Radical rethinking of manufacturing strategies is underway



# THE INTEGRATED WORKFORCE

Interactive robots

Working side-by-side with skilled labor

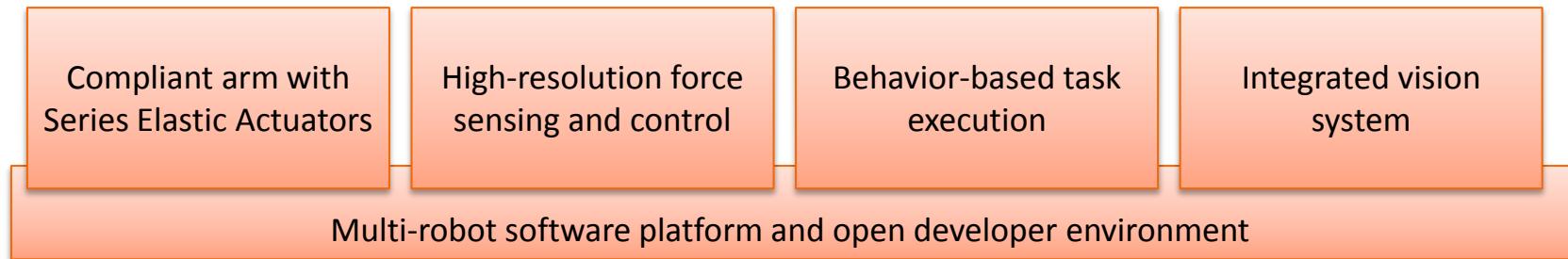
Deliver productivity, flexibility, and reduced direct labor cost



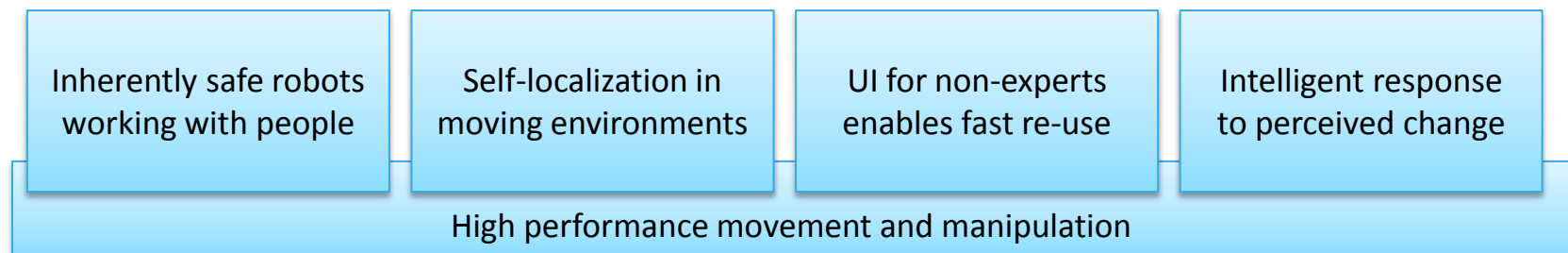
# BASED ON MANY CAPABILITIES COMBINED



## DEEP TECHNOLOGY



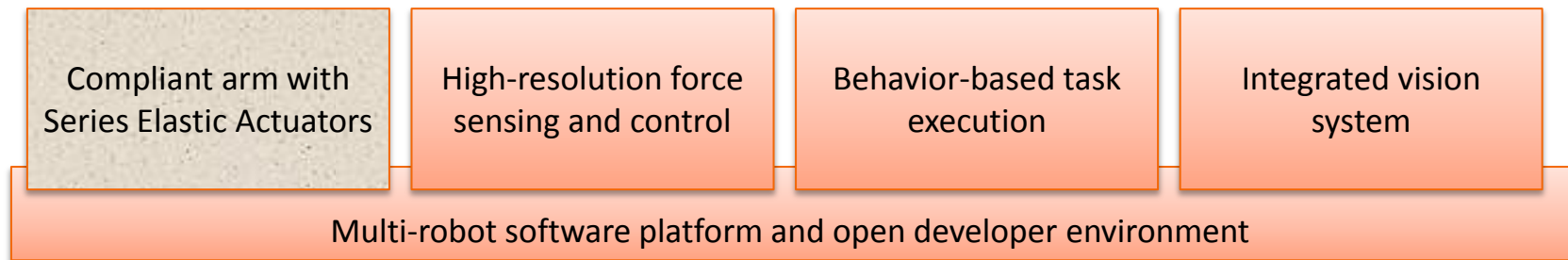
## INTELLIGENT MACHINES



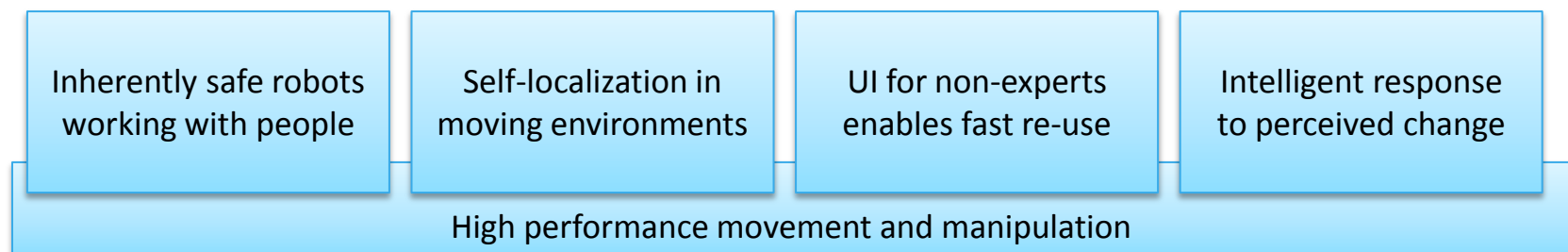
# BASED ON MANY CAPABILITIES COMBINED



## DEEP TECHNOLOGY



## INTELLIGENT MACHINES



# BASED ON MANY CAPABILITIES COMBINED



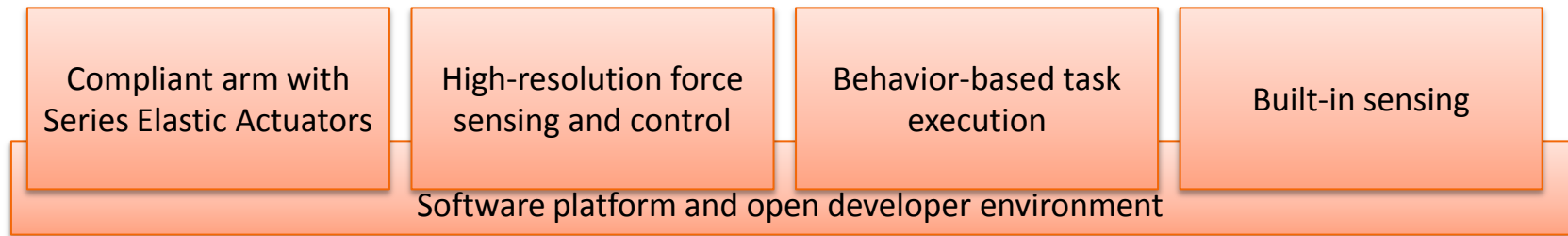
Compliant arm with  
Series Elastic Actuators

# FORCE SENSING AND CONTROL ≠ TRADITIONAL POSITION CONTROL

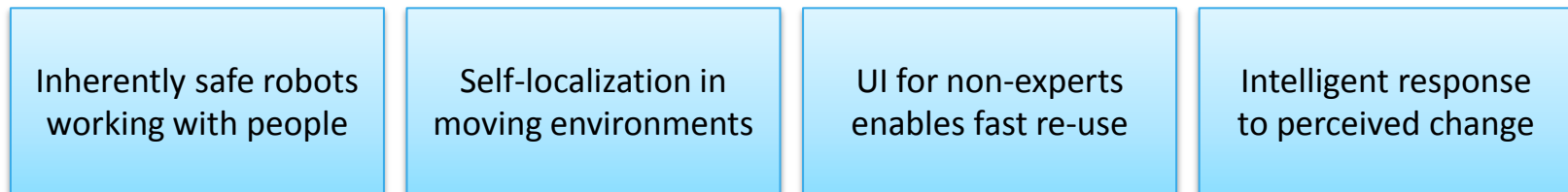


# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS

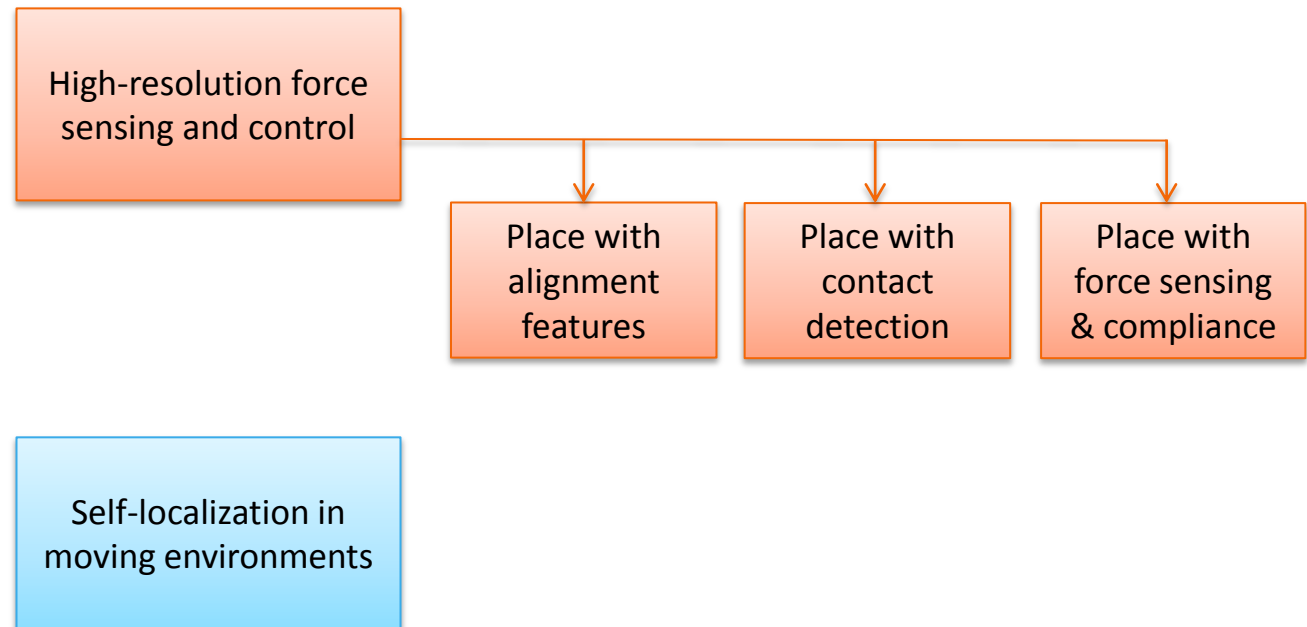
## TECHNOLOGY



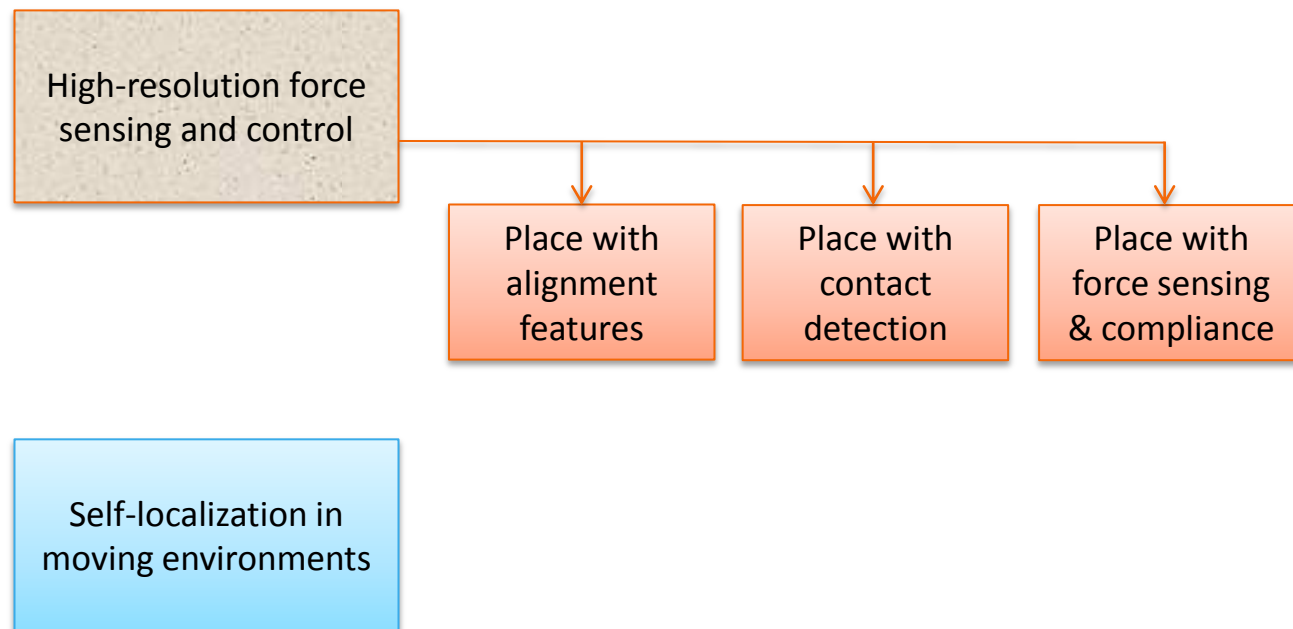
## INTELLIGENT MACHINES



# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS

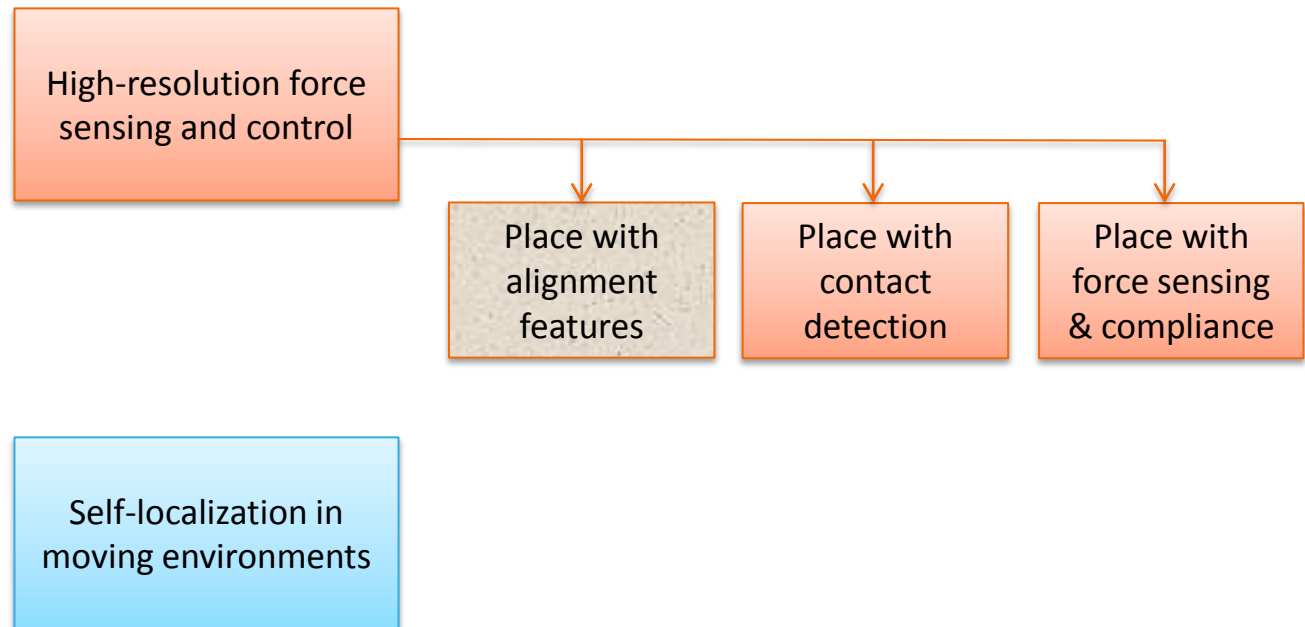


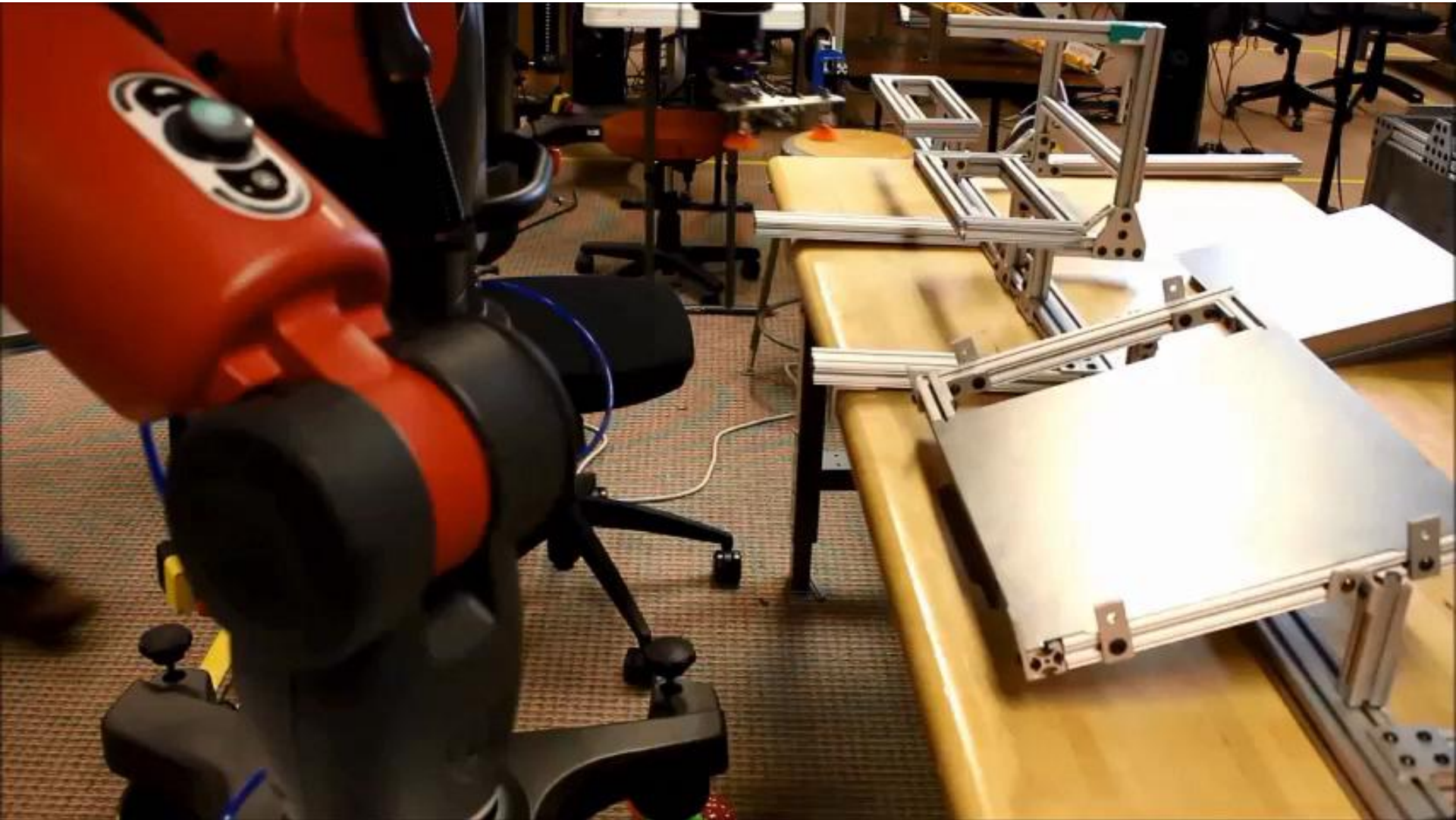
# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS



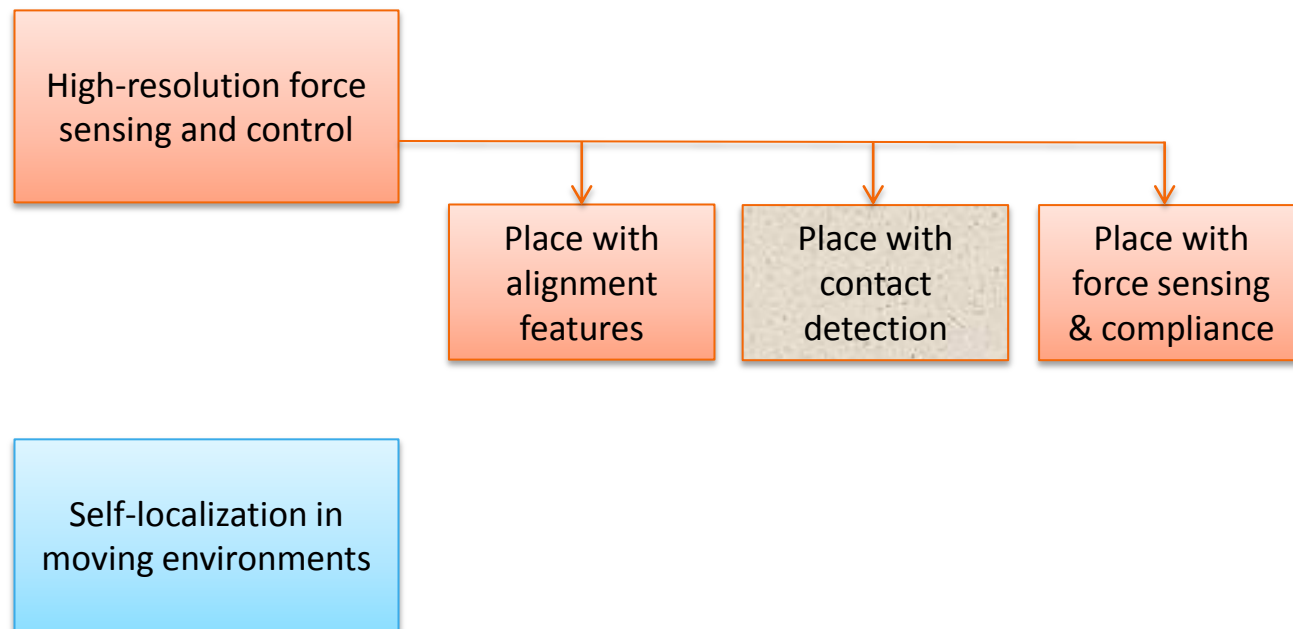


# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS



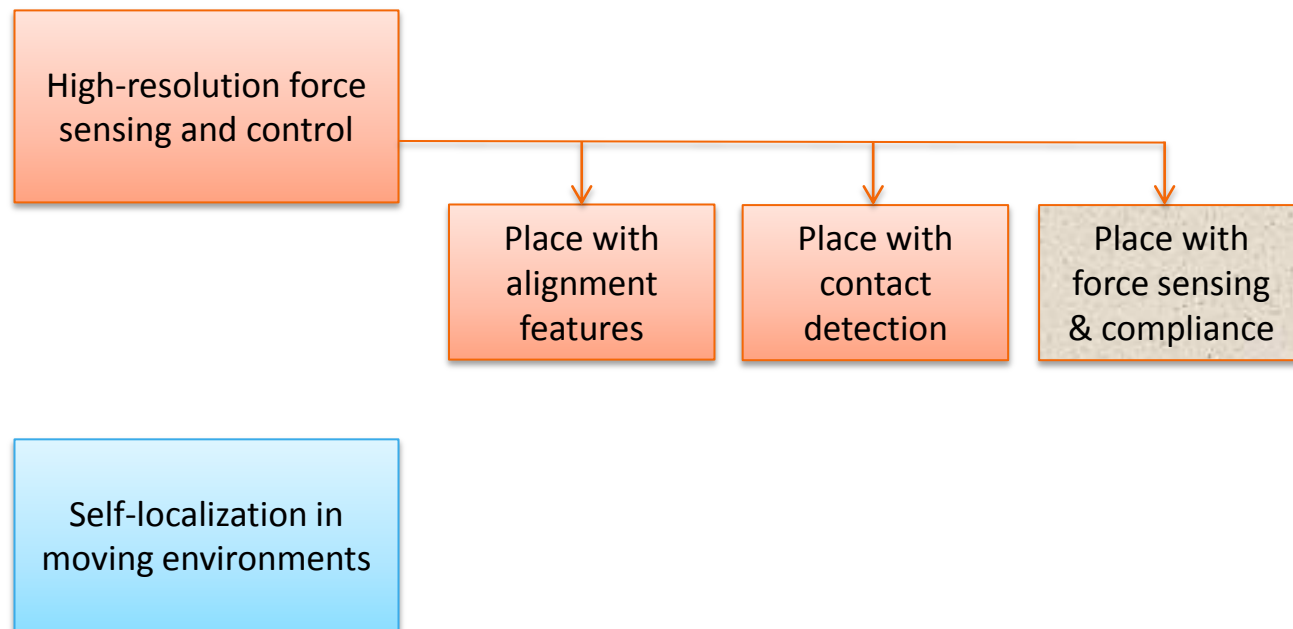


# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS



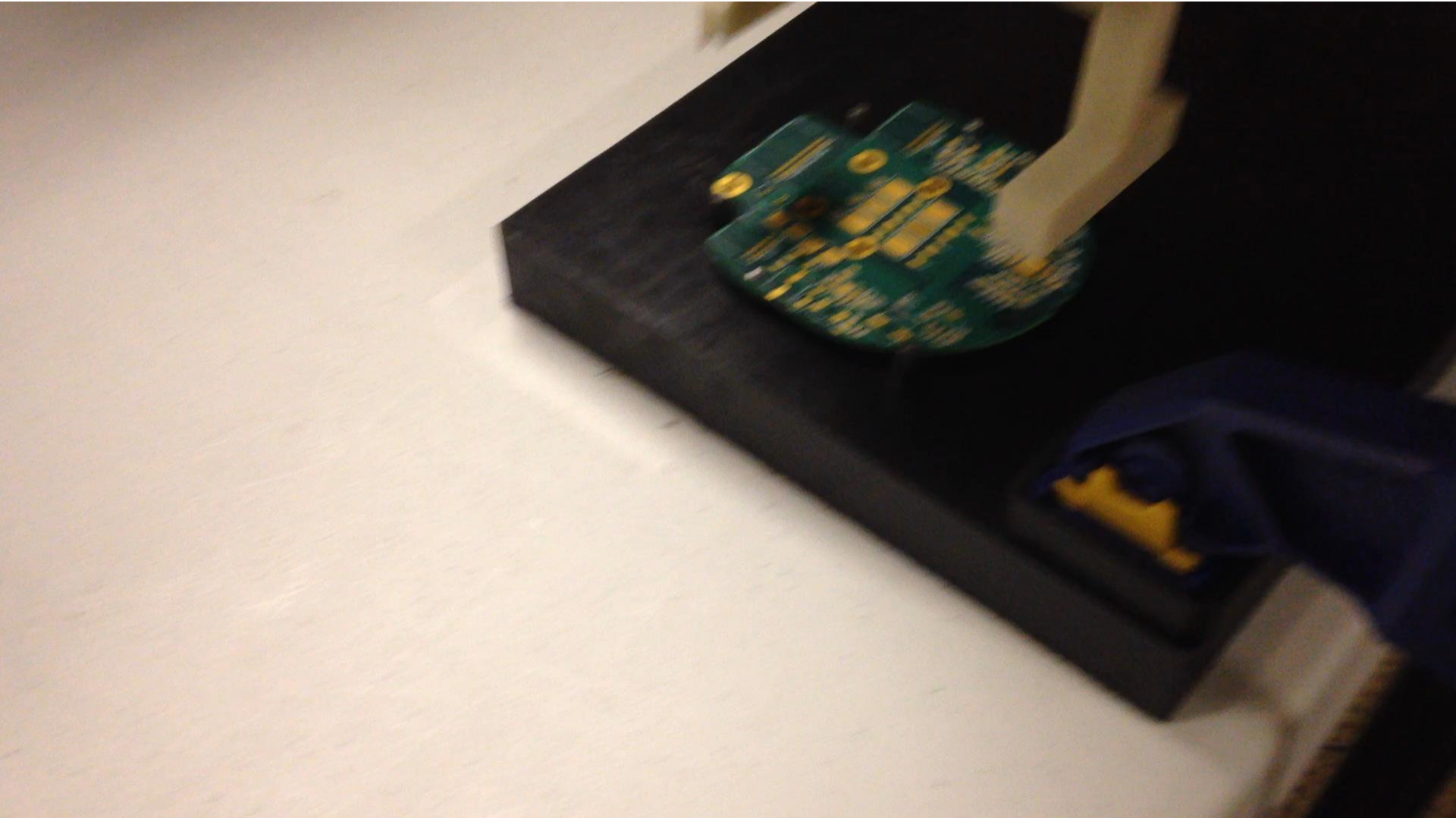


# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS

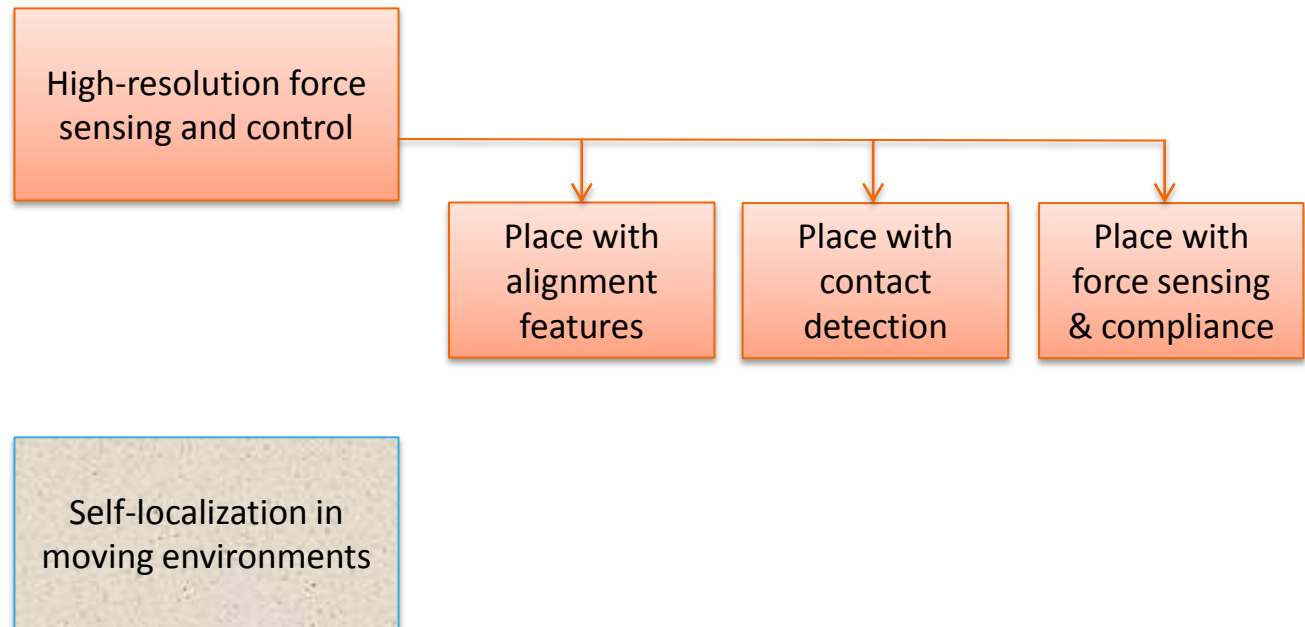




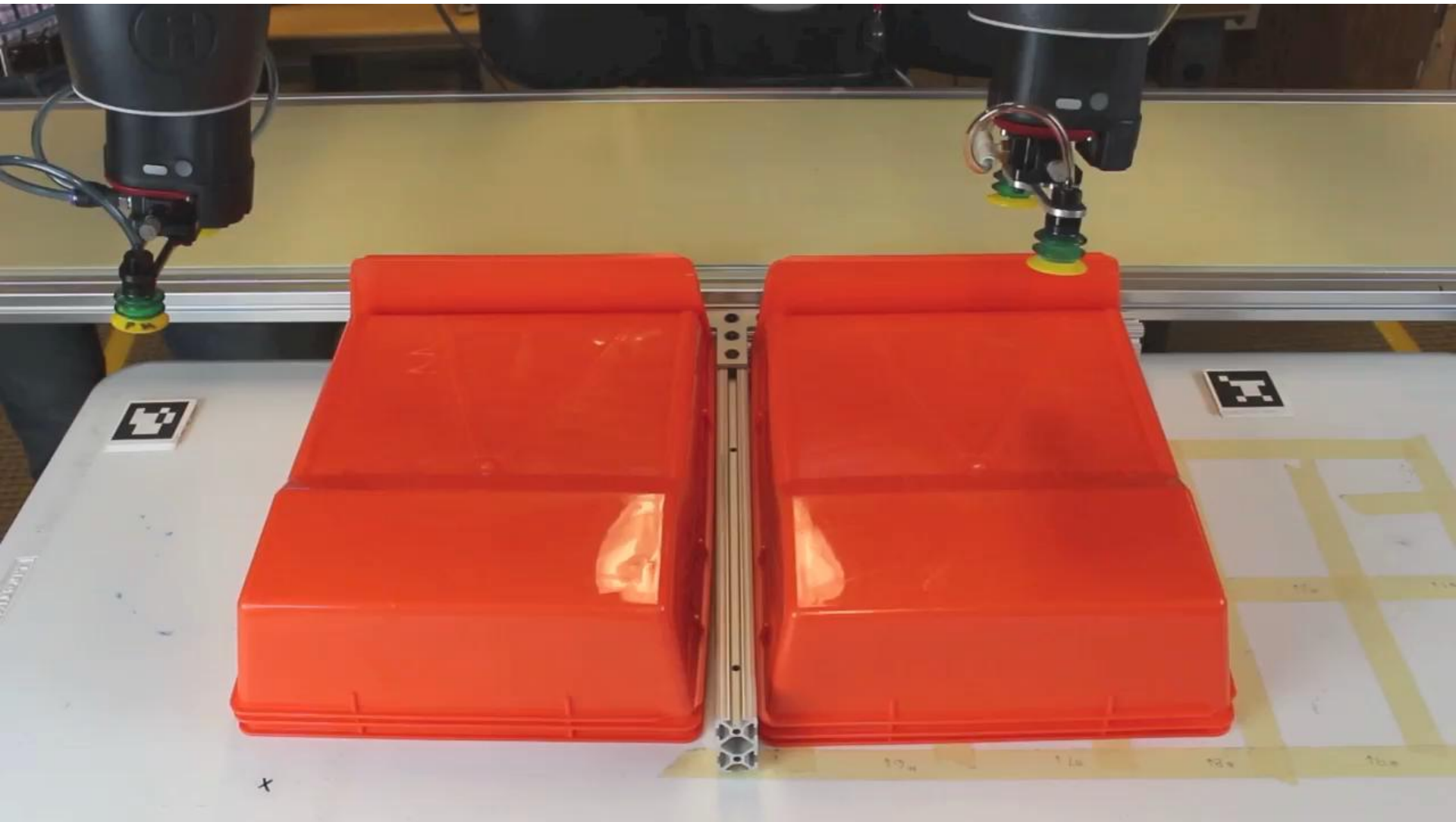
# BAXTER PLACING CIRCUIT BOARD WITH 200 MICRON ACCURACY; SENSING FORCES



# COMPONENTS FOR COLLABORATIVE, INTERACTIVE, AND INTEGRATED ROBOTS

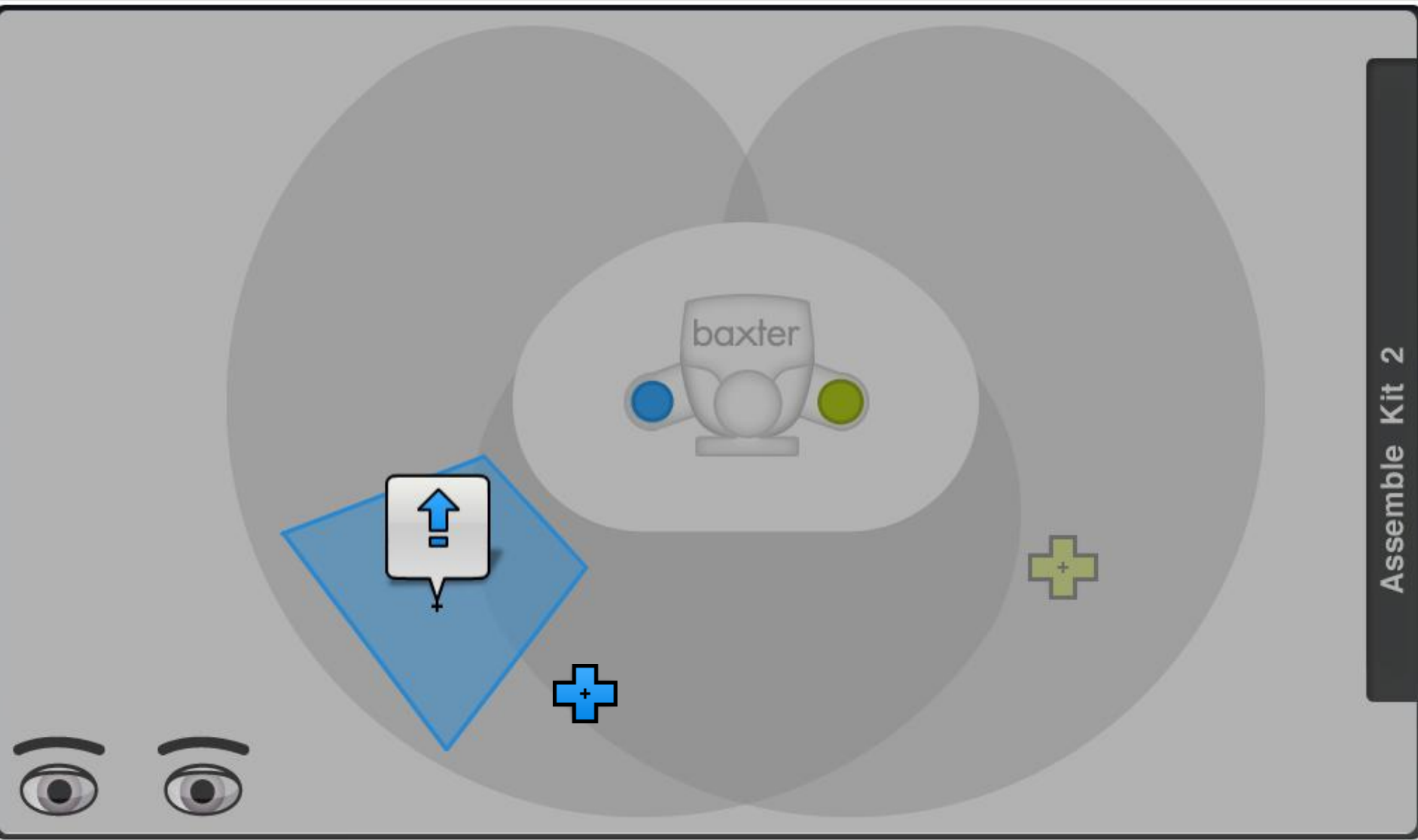


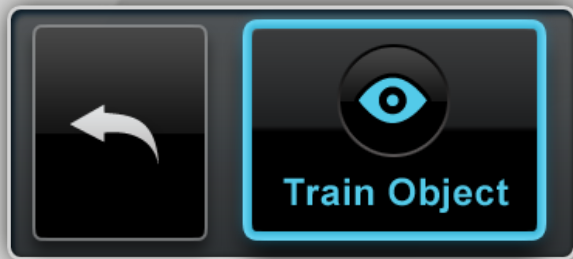




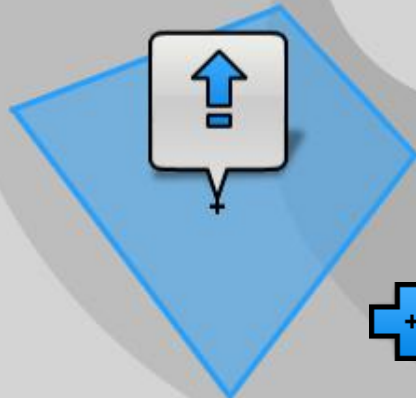
It knows what you mean and  
it does what you want.

Simple things are simple to  
train. Complex things are  
possible.





A control panel with two buttons. The left button has a white curved arrow pointing left. The right button has a blue eye icon and the text "Train Object" in white.





The main control panel features a top row of icons: a blue plus sign, a left-pointing arrow, a double-headed arrow, a right-pointing arrow, and a trash can. Below this is a central area with a blue eye icon on the left and a yellow sphere on the right. To the right of the sphere are two buttons labeled 'Moving' and 'Static', with a checkmark above the 'Static' button. At the bottom of the panel are a plus sign and a gear icon.



A callout box with a blue background and a white border, containing a white upward-pointing arrow and a camera icon.



A callout box with a white background and a black border, containing a blue downward-pointing arrow.



# AT CUSTOMER SITES

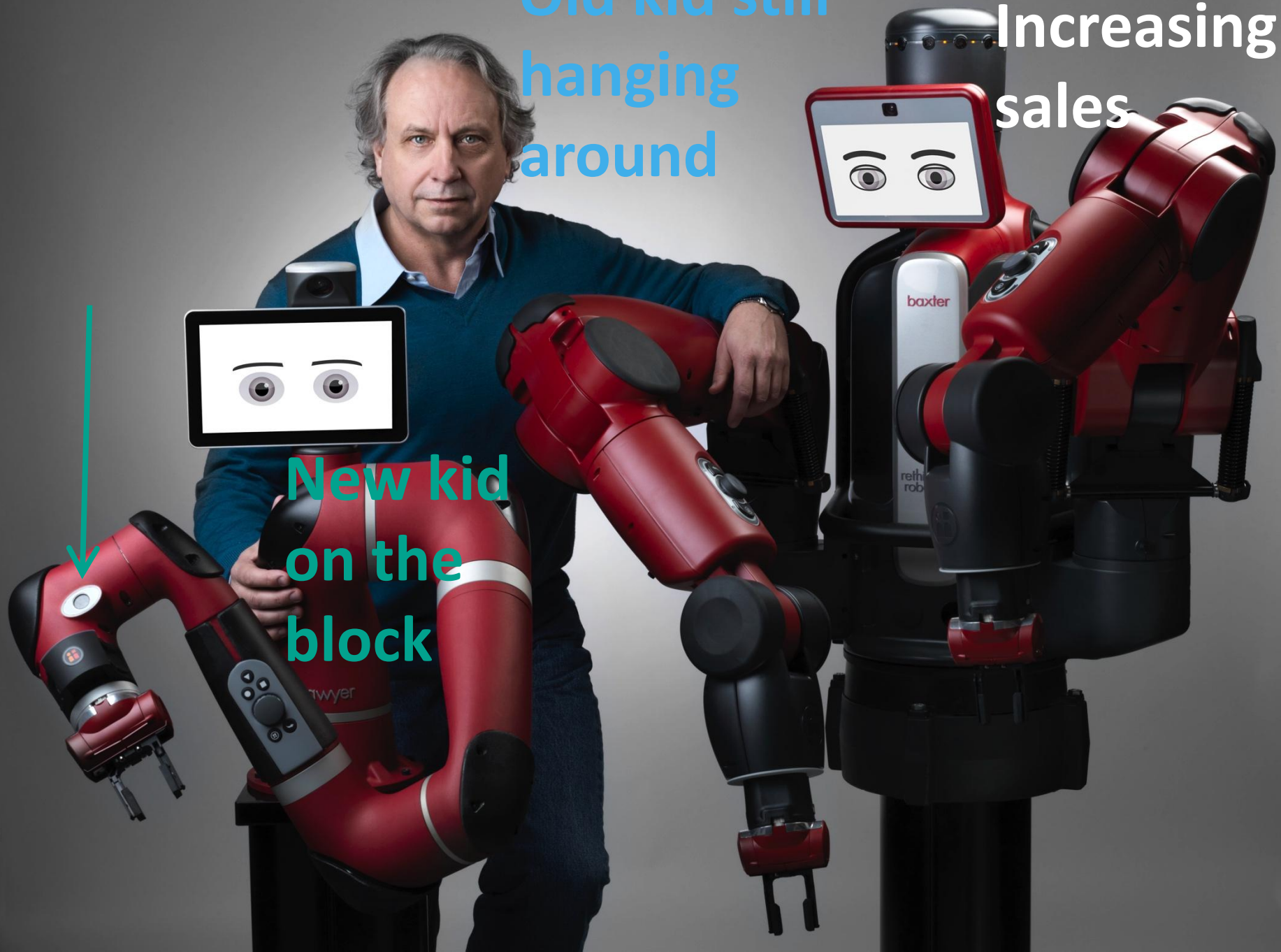




Old kid still hanging around

Increasing sales

New kid on the block













1970

1990

2010

Source: UN World Population Prospects: The 2010 Revision, Medium Variant



90%

87%



82%

80%



82%

77%

**67%**

**69%**

**64%**

1970

1990

2010

2030

2050

Source: UN World  
Population Prospects: The  
2010 Revision, Medium  
Variant



1970

1990

2010

2030

2050



eur



u.s.



china



36%

31%

33%





Surgery

Disaster relief

Driving

Fulfillment

Manufacturing

Elder care

lower cost



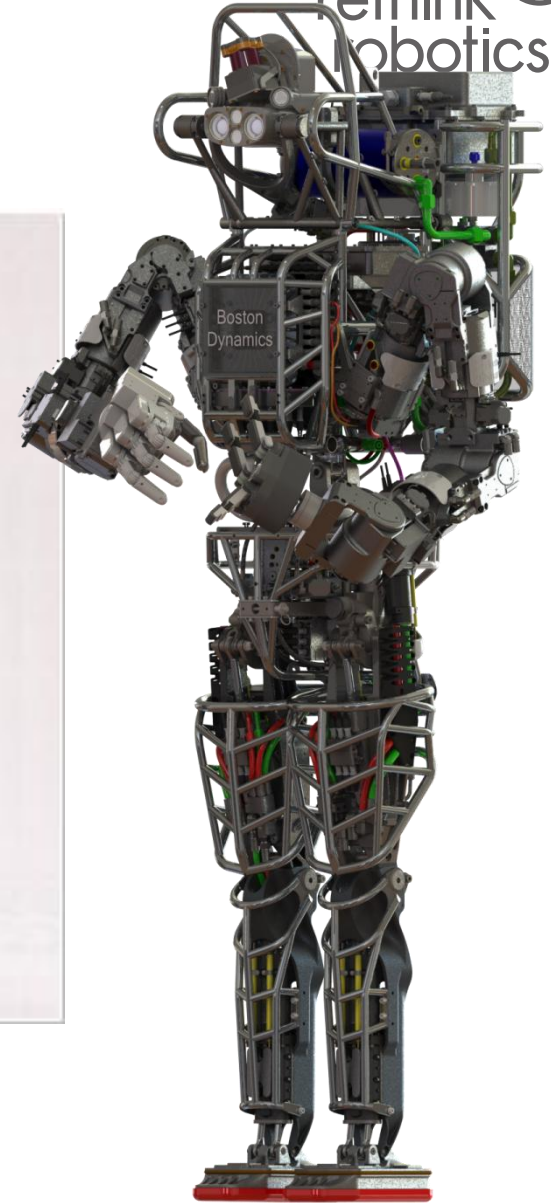


# Mobility

# Messiness

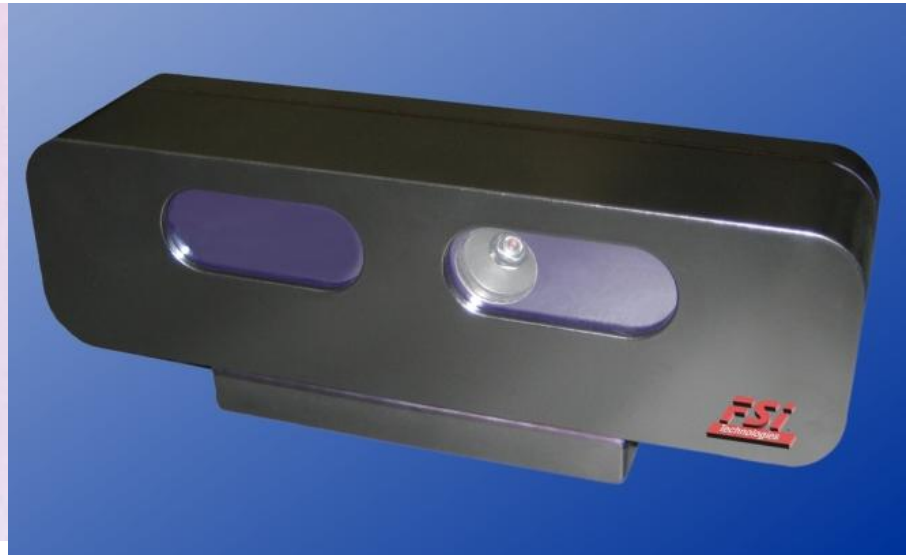
# Manipulation







Aaron Edsinger, Ph.D. thesis defense, 2006.





Robust and growing developer  
community sharing code and applications

Uses the Unified Robot Descriptor Format  
(URDF) for collaboration across groups

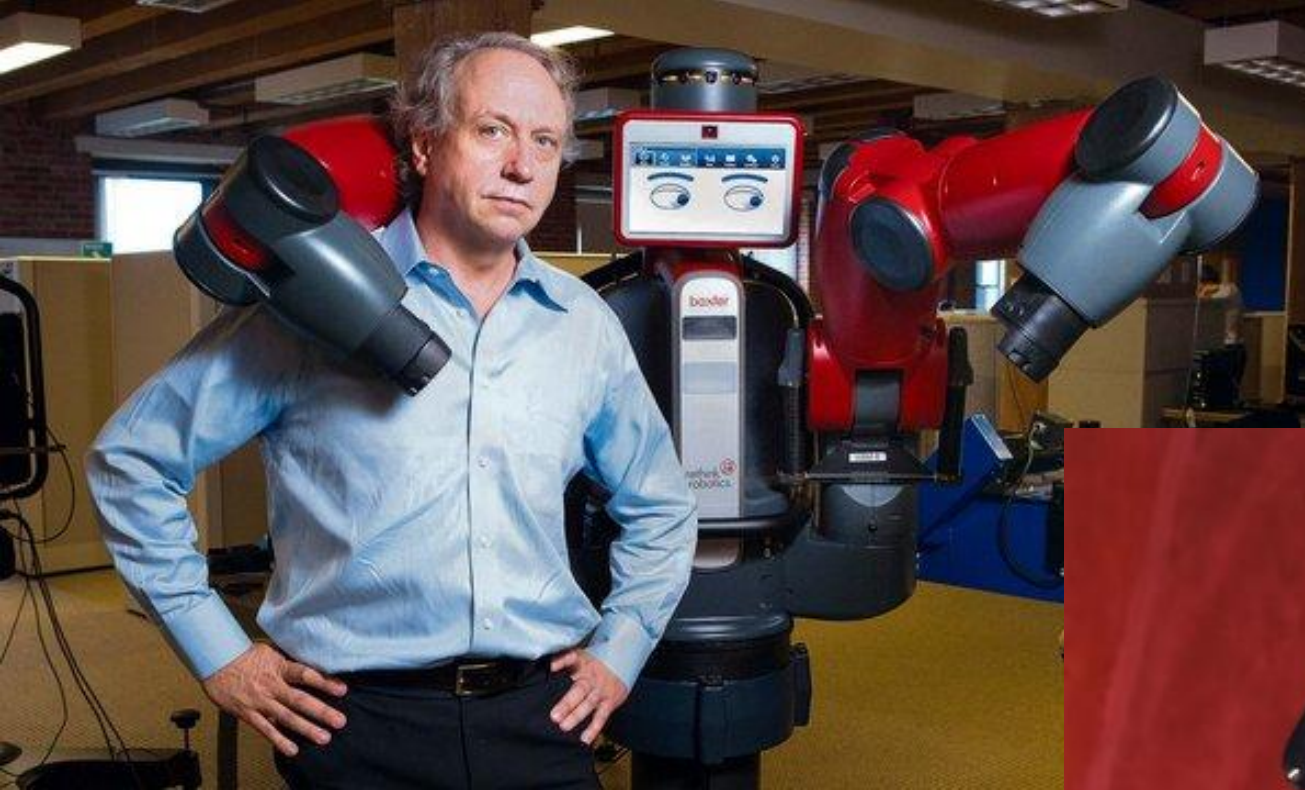
Uses open source ROS framework,  
the standard in academia and  
corporate research

Complete robotics platform with  
low-level control for custom  
application development



Interface for custom end-  
effector development

***Safety behaviors always  
operating***





# Mechanisms



# Sensors

# Materials

# Algorithms

