

# The Rise and Fall of LTL

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# Thread I: Entscheidungsproblem

**Entscheidungsproblem (The Decision Problem)**  
[Hilbert-Ackermann, 1928]: Decide if a given first-order sentence is *valid* (dually, *Satisfiable*).

**Church-Turing Theorem**, 1936: The Decision Problem is unsolvable.

**Classification Project:** Identify decidable fragments of first-order logic.

- *Monadic Class*
- *Bernays-Schönfinkel Class*
- *Ackermann Class*
- Gödel Class (w/o =)

# Monadic Logic

**Monadic Class:** First-order logic with  $=$  and monadic predicates – captures *sylogisms*.

- $(\forall x)P(x), (\forall x)(P(x) \rightarrow Q(x)) \models (\forall x)Q(x)$

[Löwenheim, 1915]: The Monadic Class is decidable.

- *Proof:* Bounded-model property – if a sentence is satisfiable, it is satisfiable in a structure of bounded size.
- *Proof technique:* quantifier elimination.

**Monadic Second-Order Logic:** Allow second-order quantification on monadic predicates.

[Skolem, 1919]: Monadic Second-Order Logic is decidable – via bounded-model property and quantifier elimination.

**Question:** What about  $<$ ?

# Thread II: Logic and Automata

Two paradigms in logic:

- **Paradigm I:** *Logic* – declarative formalism
  - Specify properties of mathematical objects, e.g.,  $(\forall x, y, z)(mult(x, y, z) \leftrightarrow mult(y, x, z))$  – commutativity.
- **Paradigm II:** *Machines* – imperative formalism
  - Specify computations, e.g., Turing machines, finite-state machines, etc.

**Surprising Phenomenon:** Intimate connection between logic and machines

# Nondeterministic Finite Automata

$$A = (\Sigma, S, S_0, \rho, F)$$

- **Alphabet:**  $\Sigma$
- **States:**  $S$
- **Initial states:**  $S_0 \subseteq S$
- **Nondeterministic transition function:**  
 $\rho : S \times \Sigma \rightarrow 2^S$
- **Accepting states:**  $F \subseteq S$

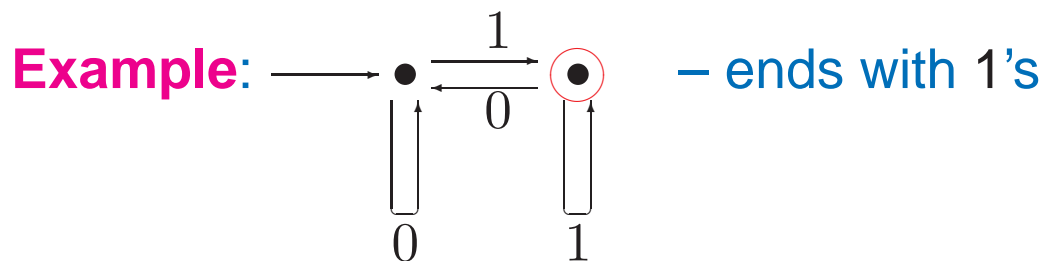
**Input word:**  $a_0, a_1, \dots, a_{n-1}$

**Run:**  $s_0, s_1, \dots, s_n$

- $s_0 \in S_0$
- $s_{i+1} \in \rho(s_i, a_i)$  for  $i \geq 0$

**Acceptance:**  $s_n \in F$

**Recognition:**  $L(A)$  – words accepted by  $A$ .



**Fact:** NFAs define the class *Reg* of regular languages.

# Logic of Finite Words

View finite word  $w = a_0, \dots, a_{n-1}$  over alphabet  $\Sigma$  as a mathematical structure:

- Domain:  $0, \dots, n - 1$
- Binary relation:  $<$
- Unary relations:  $\{P_a : a \in \Sigma\}$

## First-Order Logic (FO):

- Unary atomic formulas:  $P_a(x)$  ( $a \in \Sigma$ )
- Binary atomic formulas:  $x < y$

**Example:**  $(\exists x)((\forall y)(\neg(x < y)) \wedge P_a(x))$  – last letter is  $a$ .

## Monadic Second-Order Logic (MSO):

- Monadic second-order quantifier:  $\exists Q$
- New unary atomic formulas:  $Q(x)$

# NFA vs. MSO

**Theorem** [Büchi, Elgot, Trakhtenbrot, 1957-8 (independently)]:  $\text{MSO} \equiv \text{NFA}$

- Both MSO and NFA define the class Reg.

**Proof:** Effective

- From NFA to MSO ( $A \mapsto \varphi_A$ )
  - Existence of run – existential monadic quantification
  - Proper transitions and acceptance - first-order formula
- From MSO to NFA ( $\varphi \mapsto A_\varphi$ ): closure of NFAs under
  - *Union* – disjunction
  - *Projection* – existential quantification
  - *Complementation* – negation

# NFA Complementation

**Run Forest** of  $A$  on  $w$ :

- Roots: elements of  $S_0$ .
- Children of  $s$  at level  $i$ : elements of  $\rho(s, a_i)$ .
- Rejection: no leaf is accepting.

**Key Observation:** collapse forest into a DAG – at most one copy of a state at a level; width of DAG is  $|S|$ .

**Subset Construction** Rabin-Scott, 1959:

- $A^c = (\Sigma, 2^S, \{S_0\}, \rho^c, F^c)$
- $F^c = \{T : T \cap F = \emptyset\}$
- $\rho^c(T, a) = \bigcup_{t \in T} \rho(t, a)$
- $L(A^c) = \Sigma^* - L(A)$



# Complementation Blow-Up

$$A = (\Sigma, S, S_0, \rho, F), |S| = n$$
$$A^c = (\Sigma, 2^S, \{S_0\}, \rho^c, F^c)$$

**Blow-Up:**  $2^n$  upper bound

*Can we do better?*

**Lower Bound:**  $2^n$

Sakoda-Sipser 1978, Birget 1993

$$L_n = (0 + 1)^* 1 (0 + 1)^{n-1} 0 (0 + 1)^*$$

- $L_n$  is easy for NFA
- $\overline{L_n}$  is hard for NFA

# NFA Nonemptiness

**Nonemptiness:**  $L(A) \neq \emptyset$

**Nonemptiness Problem:** Decide if given  $A$  is nonempty.

**Directed Graph**  $G_A = (S, E)$  of NFA  $A = (\Sigma, S, S_0, \rho, F)$ :

- **Nodes:**  $S$
- **Edges:**  $E = \{(s, t) : t \in \rho(s, a) \text{ for some } a \in \Sigma\}$

**Lemma:**  $A$  is nonempty iff there is a path in  $G_A$  from  $S_0$  to  $F$ .

- Decidable in time linear in size of  $A$ , using *breadth-first search* or *depth-first search*.

# MSO Satisfiability – Finite Words

**Satisfiability:**  $models(\psi) \neq \emptyset$

**Satisfiability Problem:** Decide if given  $\psi$  is satisfiable.

**Lemma:**  $\psi$  is satisfiable iff  $A_\psi$  is nonempty.

**Corollary:** MSO satisfiability is decidable.

- Translate  $\psi$  to  $A_\psi$ .
- Check nonemptiness of  $A_\psi$ .

**Complexity:**

- *Upper Bound:* Nonelementary Growth

$$2^{\dots 2^n}$$

(tower of height  $O(n)$ )

- *Lower Bound* [Stockmeyer, 1974]: Satisfiability of FO over finite words is nonelementary (no bounded-height tower).

# Thread III: Sequential Circuits

Church, 1957: Use logic to specify sequential circuits.

**Sequential circuits:**  $C = (I, O, R, f, g, R_0)$

- $I$ : input signals
- $O$ : output signals
- $R$ : sequential elements
- $f : 2^I \times 2^R \rightarrow 2^R$ : transition function
- $g : 2^R \rightarrow 2^O$ : output function
- $R_0 \in 2^R$ : initial assignment

**Trace:** element of  $(2^I \times 2^R \times 2^O)^\omega$

$t = (I_0, R_0, O_0), (I_1, R_1, O_1), \dots$

- $R_{j+1} = f(I_j, R_j)$
- $O_j = g(R_j)$

# Specifying Traces

View infinite trace  $t = (I_0, R_0, O_0), (I_1, R_1, O_1), \dots$  as a mathematical structure:

- Domain:  $N$
- Binary relation:  $<$
- Unary relations:  $I \cup R \cup O$

## First-Order Logic (FO):

- Unary atomic formulas:  $P(x)$  ( $P \in I \cup R \cup O$ )
- Binary atomic formulas:  $x < y$

**Example:**  $(\forall x)(\exists y)(x < y \wedge P(y))$  –  $P$  holds i.o.

## Monadic Second-Order Logic (MSO):

- Monadic second-order quantifier:  $\exists Q$
- New unary atomic formulas:  $Q(x)$

**Model-Checking Problem:** Given circuit  $C$  and formula  $\varphi$ ; does  $\varphi$  hold in all traces of  $C$ ?

**Easy Observation:** Model-checking problem reducible to satisfiability problem – use FO to encode the “logic” (i.e.,  $f, g$ ) of the circuit  $C$ .

# Büchi Automata

**Büchi Automaton:**  $A = (\Sigma, S, S_0, \rho, F)$

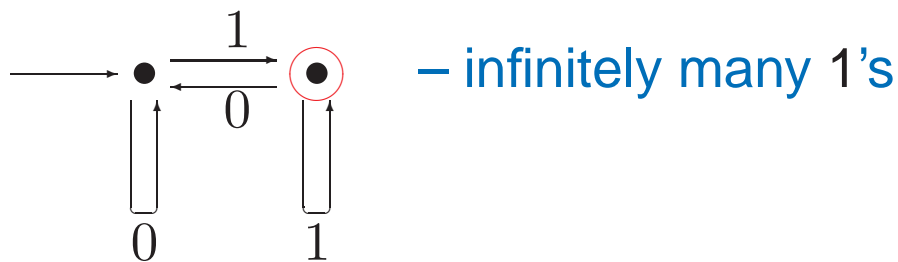
- *Alphabet:*  $\Sigma$
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- *Initial states:*  $S_0 \subseteq S$
- *Transition function:*  $\rho : S \times \Sigma \rightarrow 2^S$
- *Accepting states:*  $F \subseteq S$

**Input word:**  $a_0, a_1, \dots$

**Run:**  $s_0, s_1, \dots$

- $s_0 \in S_0$
- $s_{i+1} \in \rho(s_i, a_i)$  for  $i \geq 0$

**Acceptance:**  $F$  visited infinitely often



**Fact:** Büchi automata define the class  $\omega$ -Reg of  $\omega$ -regular languages.

# Logic vs. Automata II

**Paradigm:** Compile high-level logical specifications into low-level finite-state language

**Compilation Theorem:** [Büchi, 1960] Given an MSO formula  $\varphi$ , one can construct a Büchi automaton  $A_\varphi$  such that a trace  $\sigma$  satisfies  $\varphi$  if and only if  $\sigma$  is accepted by  $A_\varphi$ .

**MSO Satisfiability Algorithm:**

1.  $\varphi$  is satisfiable iff  $L(A_\varphi) \neq \emptyset$
2.  $L(\Sigma, S, S_0, \rho, F) \neq \emptyset$  iff there is a path from  $S_0$  to a state  $f \in F$  and a cycle from  $f$  to itself.

**Corollary** [Church, 1960]: Model checking sequential circuits wrt MSO specs is decidable.

Church, 1960: “Algorithm not very efficient” (*nonelementary complexity*, [Stockmeyer, 1974]).

# Catching Bugs with A Lasso

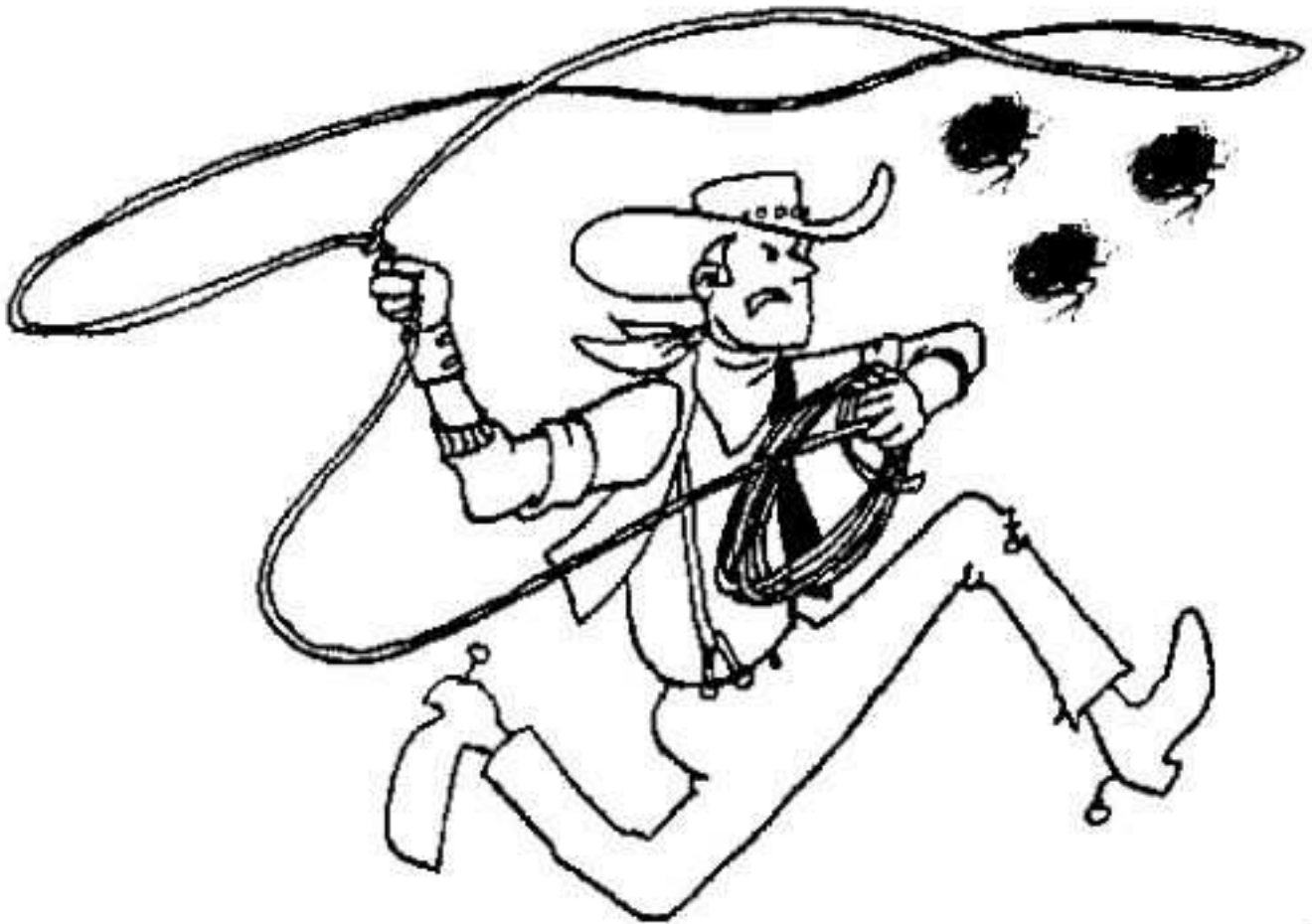
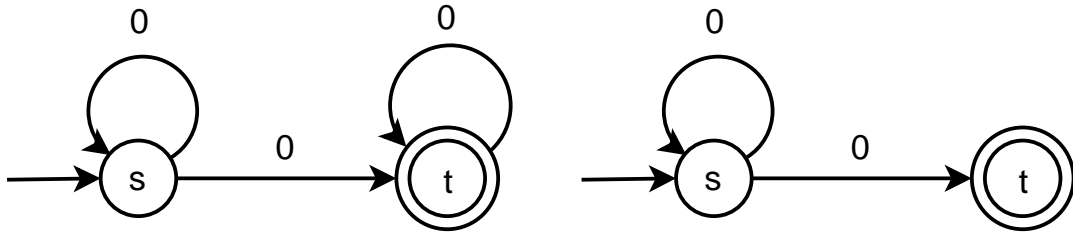


Figure 1: [Ashutosh's Blog](#), November 23, 2005



# Büchi Complementation

**Problem:** subset construction fails!



$$\rho(\{s\}, 0) = \{s, t\}, \rho(\{s, t\}, 0) = \{s, t\}$$

## History

- Büchi'62: doubly exponential construction.
- SVW'85:  $16^{n^2}$  upper bound
- Safra'88:  $n^{2n}$  upper bound
- Michel'88:  $(n/e)^n$  lower bound
- KV'97:  $(6n)^n$  upper bound
- FKV'04:  $(0.97n)^n$  upper bound
- Yan'06:  $(0.76n)^n$  lower bound
- Schewe'09:  $(0.76n)^n$  upper bound

## Thread IV: Temporal Logic

Prior, 1914–1969, Philosophical Preoccupations:

- *Religion*: Methodist, Presbyterian, atheist, agnostic
- *Ethics*: “Logic and The Basis of Ethics”, 1949
- *Free Will, Predestination, and Foreknowledge*:
  - “The future is to some extent, even if it is only a very small extent, something we can make for ourselves”.
  - “Of what will be, it has now been the case that it will be.”
  - “There is a deity who infallibly knows the entire future.”

Mary Prior: “I remember his waking me one night [in 1953], coming and sitting on my bed, . . . , and saying he thought one could make a formalised tense logic.”

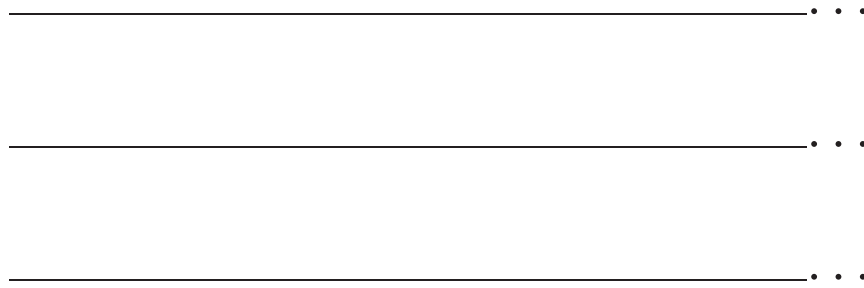
- 1957: “Time and Modality”

# Linear vs. Branching Time, A

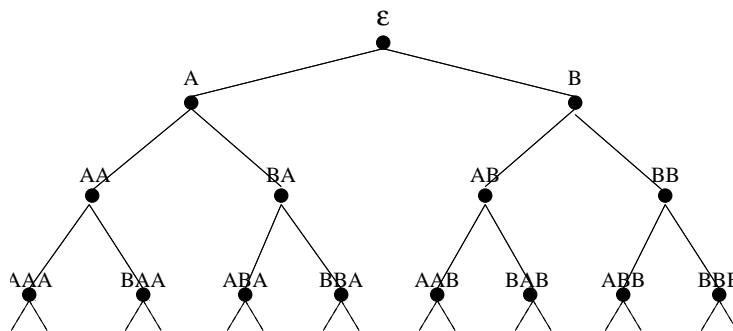
- Prior's first lecture on tense logic, Wellington University, 1954: linear time.
- Prior's "Time and modality", 1957: relationship between linear tense logic and modal logic.
- Sep. 1958, letter from Saul Kripke: "[I]n an indetermined system, we perhaps should not regard time as a linear series, as you have done. Given the present moment, there are several possibilities for what the next moment may be like – and for each possible next moment, there are several possibilities for the moment after that. Thus the situation takes the form, not of a linear sequence, but of a 'tree'". (Kripke was a high-school student, not quite 18, in Omaha, Nebraska.)

# Linear vs. Branching Time, B

- **Linear time:** a system induces a set of traces
- *Specs:* describe traces



- **Branching time:** a system induces a trace tree
- *Specs:* describe trace trees



# Linear vs. Branching Time, C

- Prior developed the idea into Ockhamist and Peircean theories of branching time (branching-time logic *without* path quantifiers)

Sample formula:  $CKM_pM_qAMK_pM_qMK_qMp$

- Burgess, 1978: “Prior would agree that the determinist sees time as a line and the indeterminist sees times as a system of forking paths.”

# Linear vs. Branching Time, D

## Philosophical Conundrum

- Prior:

- Nature of course of time – branching
- Nature of course of events – linear

- Rescher:

- Nature of time – linear
- Nature of course of events – branching
- “We have 'branching *in* time', not 'branching *of* time’”.

**Linear time:** Hans Kamp, Dana Scott and others continued the development of linear time during the 1960s.

# Temporal and Classical Logics

## Key Theorem:

- **Kamp**, 1968: Linear temporal logic with past and binary temporal connectives (“until” and “since”), over the integers, has precisely the expressive power of FO.

# The Temporal Logic of Programs

## Precursors:

- **Prior**: “There are practical gains to be had from this study too, for example in the representation of time-delay in computer circuits”
- **Rescher & Urquhart, 1971**: applications to processes (“a programmed sequence of states, deterministic or stochastic”)

### “**Big Bang 1**” [Pnueli, 1977]:

- Future linear temporal logic (LTL) as a logic for the specification of non-terminating programs
- Temporal logic with “eventually” and “always” (later, with “next” and “until”)
- Model checking via reduction to MSO and automata

**Crux**: Need to specify *ongoing behavior* rather than *input/output relation*!



# Linear Temporal Logic

**Linear Temporal logic** (LTL): logic of temporal sequences (Pnueli, 1977)

*Main feature:* time is implicit

- *next*  $\varphi$ :  $\varphi$  holds in the next state.
- *eventually*  $\varphi$ :  $\varphi$  holds eventually
- *always*  $\varphi$ :  $\varphi$  holds from now on
- $\varphi$  *until*  $\psi$ :  $\varphi$  holds until  $\psi$  holds.

•  $\pi, w \models \text{next } \varphi$  **if**  $w \bullet \xrightarrow{\varphi} \bullet \xrightarrow{\quad} \bullet \xrightarrow{\quad} \bullet \dots$

•  $\pi, w \models \varphi \text{ until } \psi$  **if**  $w \bullet \xrightarrow{\varphi} \bullet \xrightarrow{\varphi} \bullet \xrightarrow{\varphi} \bullet \xrightarrow{\psi} \bullet \dots$

# Examples

- always not ( $CS_1$  and  $CS_2$ ): mutual exclusion (safety)
- always (Request implies eventually Grant): liveness
- always (Request implies (Request until Grant)): liveness

# Expressive Power

- Gabbay, Pnueli, Shelah & Stavi, 1980: Propositional LTL over the naturals has precisely the expressive power of FO.
- Thomas, 1979: FO over naturals has the expressive power of star-free  $\omega$ -regular expressions

**Summary:** LTL=FO=star-free  $\omega$ -RE < MSO= $\omega$ -RE

Meyer on LTL, 1980, in “Ten Thousand and One Logics of Programming”:

“The corollary due to Meyer – I have to get in my controversial remark – is that that [GPSS’80] makes it theoretically uninteresting.”

# Computational Complexity

**Recall:** Satisfiability of FO over traces is non-elementary

## Contrast with LTL:

- Wolper, 1981: LTL satisfiability is in EXPTIME.
- Halpern&Reif, 1981, Sistla&Clarke, 1982: LTL satisfiability is PSPACE-complete.

**Basic Technique:** *tableau* (influenced by branching-time techniques)

# PLTL

Lichtenstein, Pnueli, & Zuck, 1985: past-time connectives are useful in LTL:

- yesterday  $q$ :  $q$  was true in the previous state
- past  $p$ :  $q$  was true sometime in the past
- $p$  since  $q$ :  $p$  has been true since  $q$  was true

**Example:** always ( $rcv \rightarrow$  past snt)

## Theorem

- Expressively equivalent to LTL [LPZ'85]
- Satisfiability of PLTL is PSPACE-complete [LPZ'85]
- PLTL is exponentially more succinct than LTL [Markey, 2002]

# Model Checking

**“Big Bang 2”** [Clarke & Emerson, 1981, Queille & Sifakis, 1982]: Model checking programs of size  $m$  wrt CTL formulas of size  $n$  can be done in time  $mn$ .

**Linear-Time Response** [Lichtenstein & Pnueli, 1985]: Model checking programs of size  $m$  wrt LTL formulas of size  $n$  can be done in time  $m2^{O(n)}$  (*tableau*-based).

**Seemingly:**

- *Automata*: Nonelementary
- *Tableaux*: exponential

# Back to Automata

## Exponential-Compilation Theorem:

[V. & Wolper, 1983–1986]

Given an LTL formula  $\varphi$  of size  $n$ , one can construct a Büchi automaton  $A_\varphi$  of size  $2^{O(n)}$  such that a trace  $\sigma$  satisfies  $\varphi$  if and only if  $\sigma$  is accepted by  $A_\varphi$ .

### Automata-Theoretic Algorithms:

#### 1. *LTL Satisfiability:*

$\varphi$  is satisfiable iff  $L(A_\varphi) \neq \emptyset$  (PSPACE)

#### 2. *LTL Model Checking:*

$M \models \varphi$  iff  $L(M \times A_{\neg\varphi}) = \emptyset$  ( $m2^{O(n)}$ )

Vardi, 1988: Also with past.

# Reduction to Practice

## Practical Theory:

- Courcoubetis, V., Yannakakis & Wolper, 1989: Optimized search algorithm for explicit model checking
- Burch, Clarke, McMillan, Dill & Hwang, 1990: Symbolic algorithm for LTL compilation
- Clarke, Grumberg & Hamaguchi, 1994: Optimized symbolic algorithm for LTL compilation
- Gerth, Peled, V. & Wolper, 1995: Optimized explicit algorithm for LTL compilation

## Implementation:

- COSPAN [Kurshan, 1983]: deterministic automata specs
- Spin [Holzmann, 1995]: Promela w. LTL:
- SMV [McMillan, 1995]: SMV w. LTL

*Satisfactory solution to Church's problem?*  
Almost, but not quite, since  $LTL < MSO = \omega\text{-RE}$ .



# Enhancing Expressiveness

- Wolper, 1981: Enhance LTL with grammar operators, retaining EXPTIME-ness (PSPACE [SC'82])
- V. & Wolper, 1983: Enhance LTL with automata, retaining PSPACE-completeness
- Sistla, V. & Wolper, 1985: Enhance LTL with 2nd-order quantification, losing elementariness
- V., 1989: Enhance LTL with fixpoints, retaining PSPACE-completeness

**Bottom Line:** ETL (LTL w. automata) =  $\mu$ TL (LTL w. fixpoints) = MSO, and has exponential-  
compilation property.

# Thread V: Dynamic and Branching-Time Logics

## Dynamic Logic [Pratt, 1976]:

- The  $\Box\varphi$  of modal logic can be taken to mean “ $\varphi$  holds after an execution of a program step”.
- Dynamic modalities:
  - $[\alpha]\varphi$  –  $\varphi$  holds after all executions of  $\alpha$ .
  - $\psi \rightarrow [\alpha]\varphi$  corresponds to Hoare triple  $\{\psi\}\alpha\{\varphi\}$ .

**Propositional Dynamic Logic** [Fischer & Ladner, 1977]: *Boolean* propositions, programs – *regular expressions over atomic* programs.

**Satisfiability** [Pratt, 1978]: EXPTIME – using *tableau*-based algorithm

**Extensions to nonterminating programs** [Streett 1981, Harel & Sherman 1981] – awkward compared to linear temporal logic.

# Branching-Time Logic

## From dynamic logic back to temporal logic:

The dynamic-logic view is clearly branching; what is the analog for temporal logic?

- Emerson & Clarke, 1980: correctness properties as fixpoints over computation trees
- Ben-Ari, Manna & Pnueli, 1981: branching-time logic UB; satisfiability in EXPTIME using tableaux
- Clarke & Emerson, 1981: branching-time logic CTL; efficient model checking
- Emerson & Halpern, 1983: branching-time logic CTL\* – ultimate branching-time logic

## Key Idea: Prior missed *path quantifiers*

- $\forall$  eventually  $p$ : on all possible futures,  $p$  eventually happen.

# Linear vs. Branching Temporal Logics

- **Linear time:** a system generates a set of computations
- **Specs:** describe computations
- **LTL:**  $\textit{always}(\text{request} \rightarrow \textit{eventually} \text{ grant})$
  
- **Branching time:** a system generates a computation tree
- **Specs:** describe computation trees
- **CTL:**  $\forall \textit{always} (\text{request} \rightarrow \forall \textit{eventually} \text{ grant})$

# Combining Dynamic and Temporal Logics

## Two distinct perspectives:

- Temporal logic: *state based*
- Dynamic logic: *action based*

## Symbiosis:

- Harel, Kozen & Parikh, 1980: Process Logic (branching time)
- V. & Wolper, 1983: Yet Another Process Logic (branching time)
- Harel and Peleg, 1985: Regular Process Logic (linear time)
- Henriksen and Thiagarajan, 1997: Dynamic LTL (linear time)

## Tech Transfer:

- Beer, Ben-David & Landver, IBM, 1998: RCTL (branching time)
- Beer, Ben-David, Eisner, Fisman, Gringauze, Rodeh, IBM, 2001: Sugar (branching time)

# Thread V: From LTL to PSL

## Model Checking at Intel

### *Prehistory:*

- 1990: successful feasibility study using Kurshan's COSPAN
- 1992: a pilot project using CMU's SMV
- 1995: an internally developed (linear time) property-specification language

### *History:*

- 1997: Development of 2nd-generation technology started (engine and language)
- 1999: BDD-based model checker released
- 2000: SAT-based model checker released
- 2000: *ForSpec* (language) released

# Dr. Vardi Goes to Intel

1997: (w. Fix, Hadash, Kesten, & Sananes)

V.: How about LTL?

F., H., K., & S.: Not expressive enough.

V.: How about ETL?  $\mu$ TL?

F., H., K., & S.: Users will object.

1998 (w. Landver)

V.: How about ETL?

L.: Users will object.

L.: How about regular expressions?

V.: They are equivalent to automata!

**RELTL:** LTL plus dynamic modalities,  
interpreted linearly –  $[e]\varphi$

E.g.:  $[\text{true}^*, \text{send}, \text{!cancel}]\text{sent}$

**Easy:** RELTL=ETL= $\omega$ -RE

*ForSpec:* RELTL + hardware features (clocks and resets) [Armoni, Fix, Flaisher, Gerth, Ginsburg, Kanza, Landver, Mador-Haim, Singerman, Tiemeyer, V., Zbar]

# From ForSpec to PSL

## Industrial Standardization:

- Process started in 2000
- Four candidates: IBM's Sugar, Intel's ForSpec, Motorola's CBV, and Verisity's E.
- Fierce debate on linear vs. branching time

## Outcome:

- Big political win for IBM (see references to PSL/Sugar)
- Big technical win for Intel
  - PSL is LTL + RE + clocks + resets
  - Branching-time extension as an acknowledgement to Sugar
  - Some evolution over time in hardware features
- Major influence on the design of **SVA** (another industrial standard)

**Bottom Line:** *Huge* push for model checking in industry.



## Thread VI: What about the Past?

- Avoided in industrial languages due to implementation challenges
- Less important in model checking; if past events are important, then program would keep track of them.
- But, the past is important in specification (LPZ'85)!

Dax, Klaedtke, & Lange, 2009: *Regular Temporal Logic* (RTL)

- PLTL
- Dynamic modalities:  $\langle e \rangle \varphi$
- Past Dynamic modalities:  $\langle e \rangle^- \varphi$

### Theorem [DKL'09]

- Expressively equivalent to RELTL.
- Exponentially more succinct than RELTL.
- Satisfiability is PSPACE-complete

# Linear Dynamic Logic (LDL)

## Observations:

- Dynamic modalities subsume temporal connectives, e.g., eventually  $q$  is equivalent to  $\langle \text{true}^* \rangle q$
- To capture past, add *reverse* operator to REs.
  - $a$ : “consume”  $a$  and move forward.
  - $a^-$ : “consume”  $a$  and move backward.

## Inspiration:

- PDL+converse [Pratt, 1976]
- Two-way navigation in XPath

## Theorem:

- Expressively equivalent to RELTL.
- Exponentially more succinct than RELTL.
- Satisfiability is PSPACE-complete.

# LTL is Dead, Long Live LDL!

## What was important about PLTL?

- Linear time
- Simple syntax
- Exponential-compilation property
- *Equivalence to FO*

## What is important about LDL?

- Linear time
- Exponential-compilation property
- *Equivalence to MSO*
- Extremely simple syntax: REs (with *reverse*) and dynamic modalities

**Also:** easy to pronounce :-)

# Some Philosophical Points

- Science is a cathedral; we are the masons.
- There is no architect; outcome is unpredictable.
- Most of our contributions are smaller than we'd like to think.
- Even small contributions can have major impact.
- Much is forgotten and has to be rediscovered.
- Rediscovering the past helps us move into the future.